

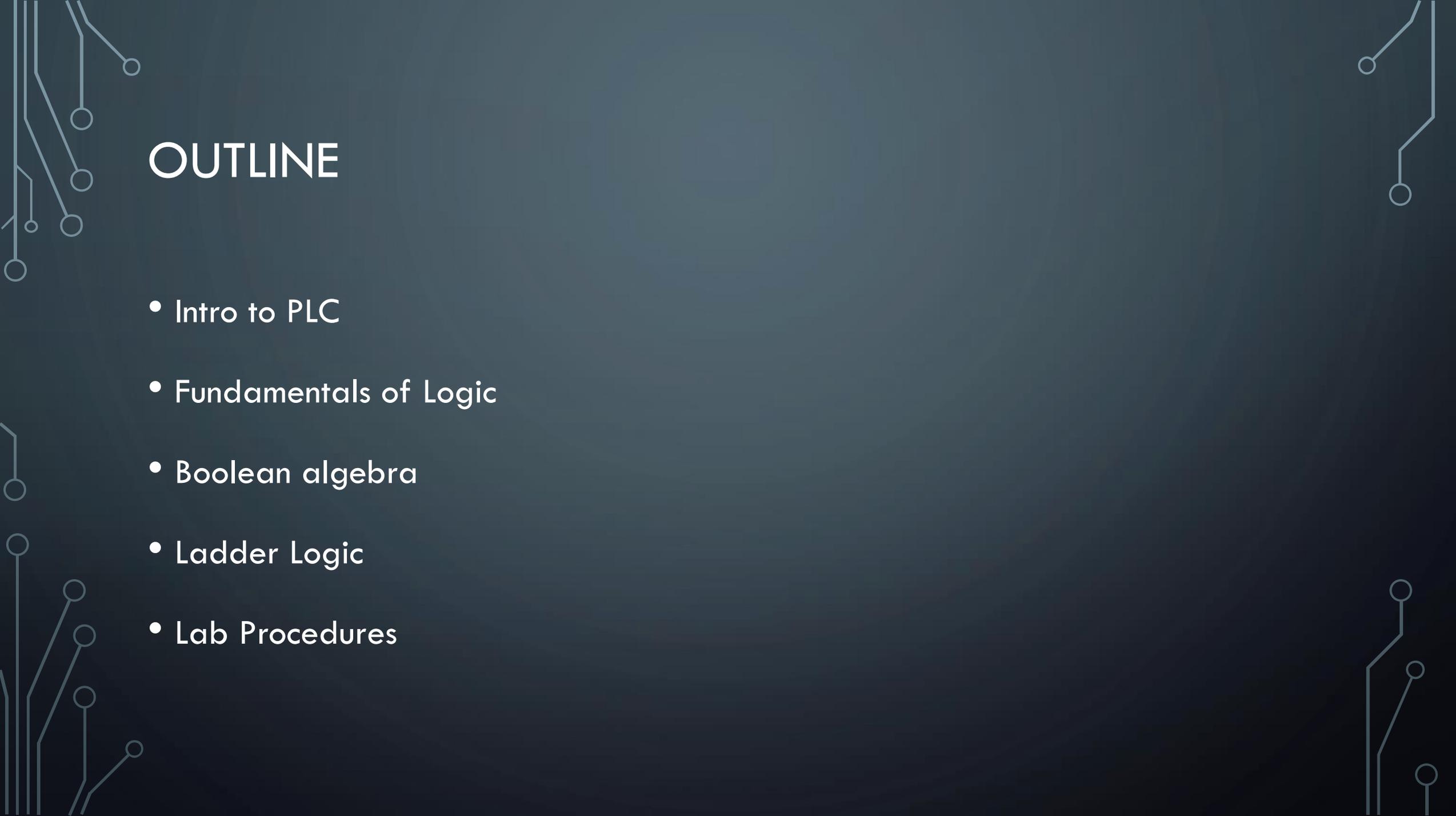


# PROGRAMMABLE LOGIC CONTROLLERS

LAB 3

# SCHEDULE

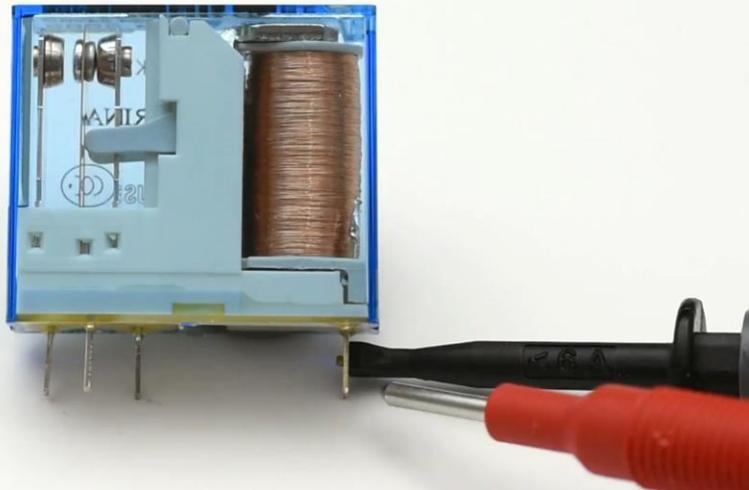
3	September 16 Forced and Free Vibrations Part II Gear Systems	September 16, 18 Forced and Free Vibrations Part II Gear Systems
4	September 23 No Lecture	September 23, 27 Forced and Free Vibrations Part II Gear Systems
5	September 30 Exam I PLC Tank	September 30, October 16 PLC Tank
6	October 7 No Lecture	October 9, 11 PLC Tank
7	October 14 Control Theory Unstable Systems	October 14, 18 Control Theory Unstable Systems

The slide features a dark blue background with decorative white circuit board traces in the corners. The top-left and bottom-left corners have more complex, branching patterns, while the top-right and bottom-right corners have simpler, more linear traces. The word "OUTLINE" is centered in the upper half of the slide in a large, white, sans-serif font.

# OUTLINE

- Intro to PLC
- Fundamentals of Logic
- Boolean algebra
- Ladder Logic
- Lab Procedures

# RELAY CONTROLLED LOGIC



Copthorne Central - Lift motor room #2  
On the roof of this 12 Story Building is,



PLC

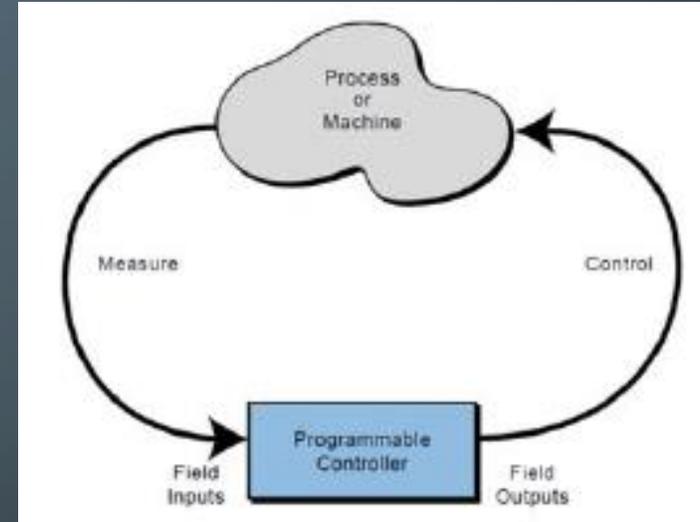
VS



Relay  
Logic

# PROGRAMMABLE LOGIC CONTROLLERS

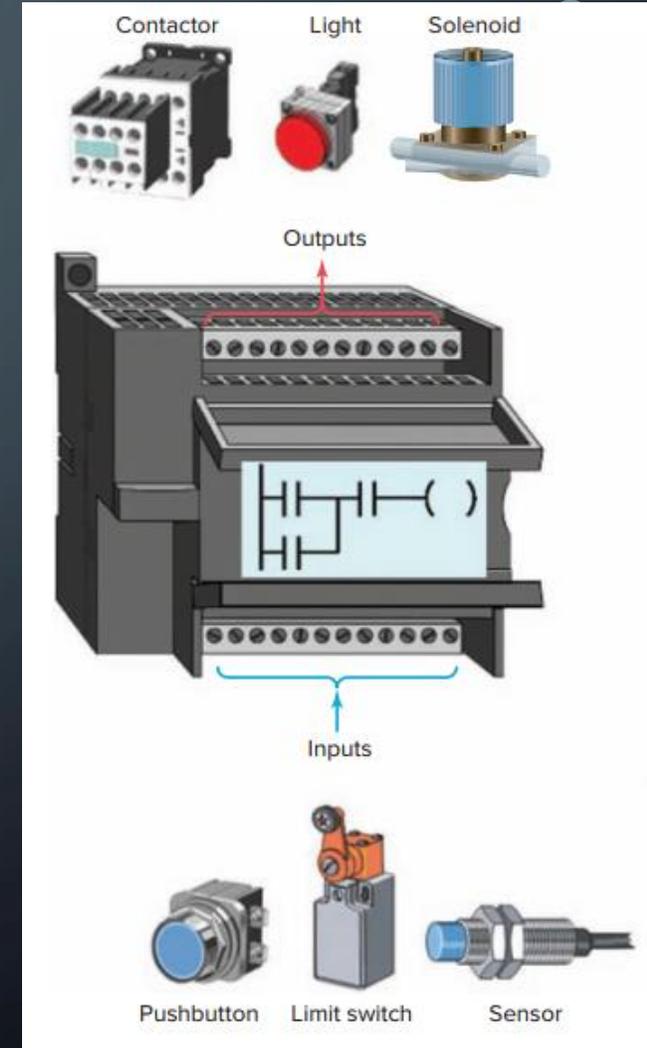
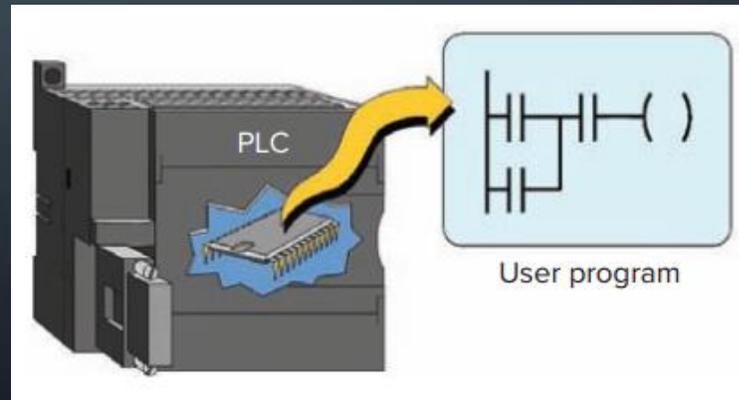
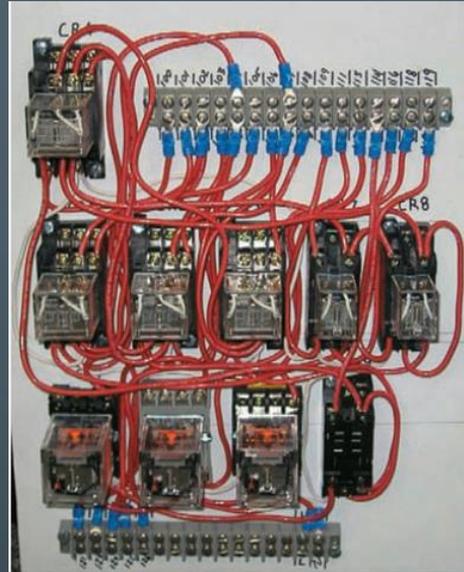
- PLC: real-time system
- Replace relay logic
- Functions
  - Relay switch
  - Timing
  - Counting
  - Signal processing



# PROGRAMMABLE LOGIC CONTROLLERS

- Benefits

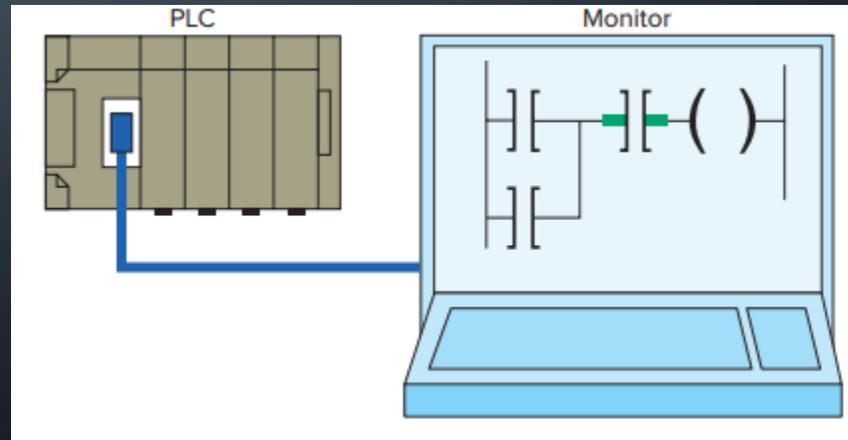
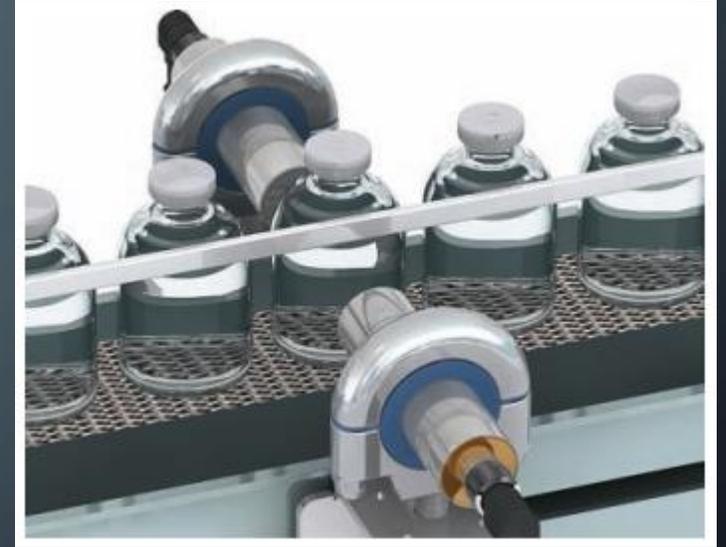
- Increased Reliability
- More Flexibility
- Lower Cost
- Communications Capability
- Faster Response Time
- Easier to Troubleshoot
- Easier to Test Field Devices



# PROGRAMMABLE LOGIC CONTROLLERS

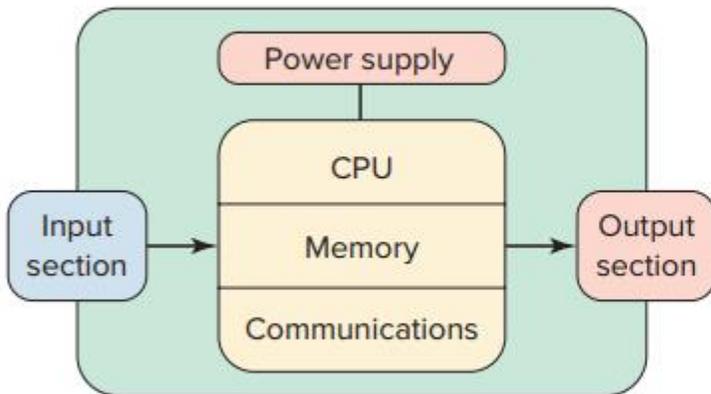
- Benefits

- Increased Reliability
- More Flexibility
- Lower Cost
- Communications Capability
- Faster Response Time
- Easier to Troubleshoot
- Easier to Test Field Devices

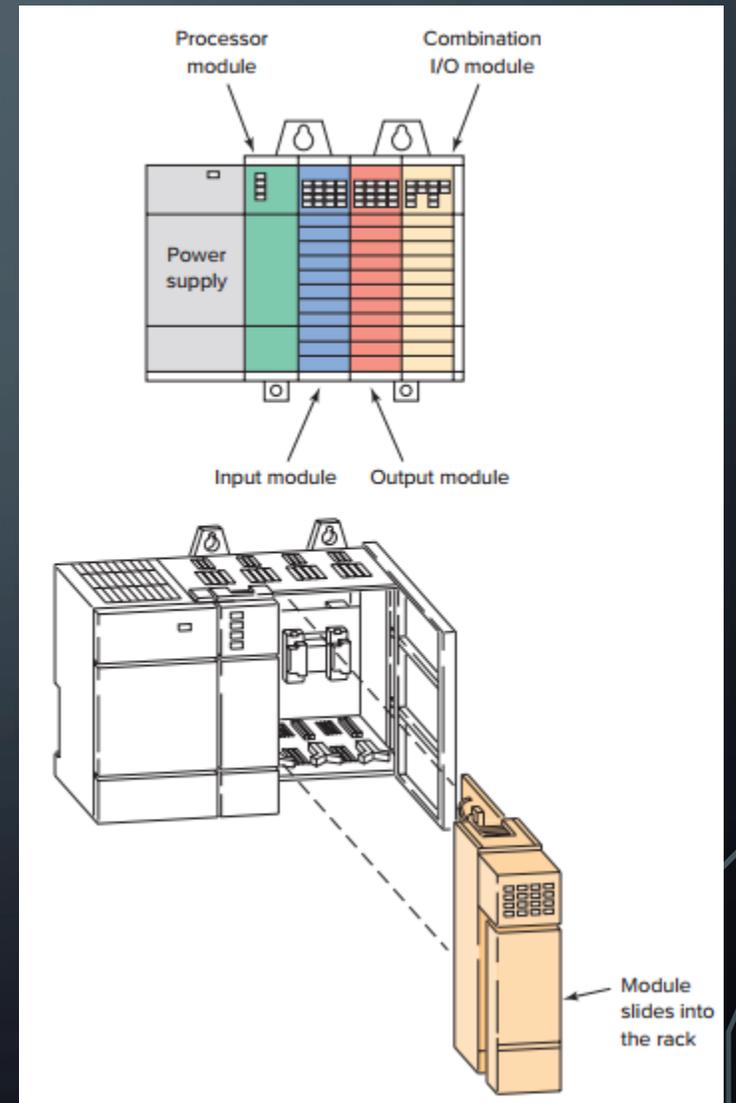


# PARTS OF PLC

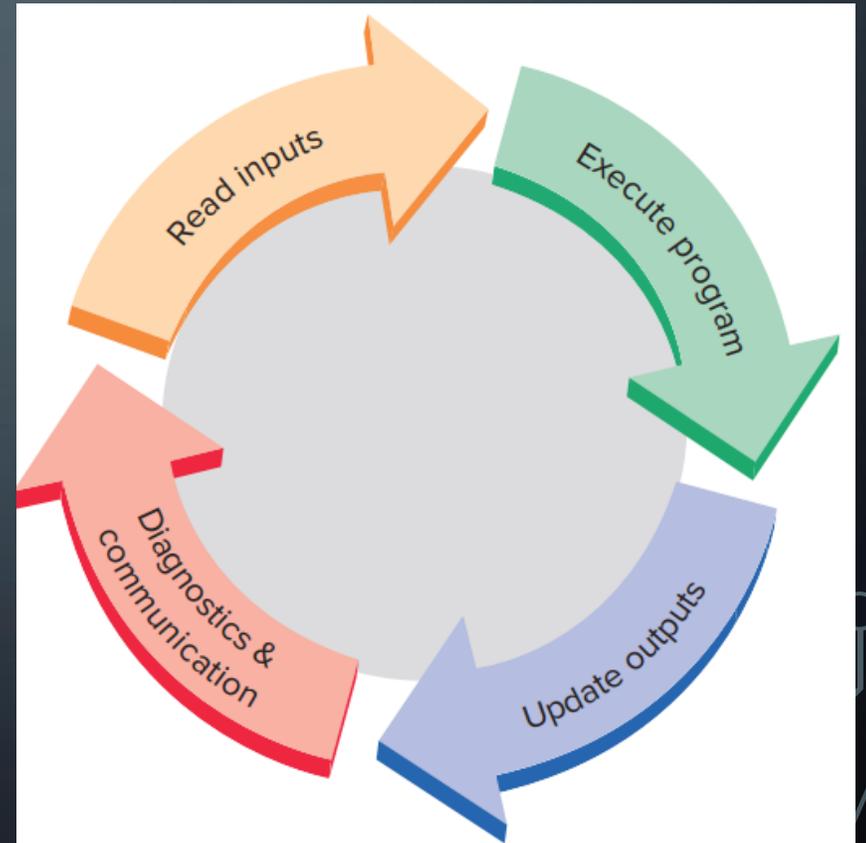
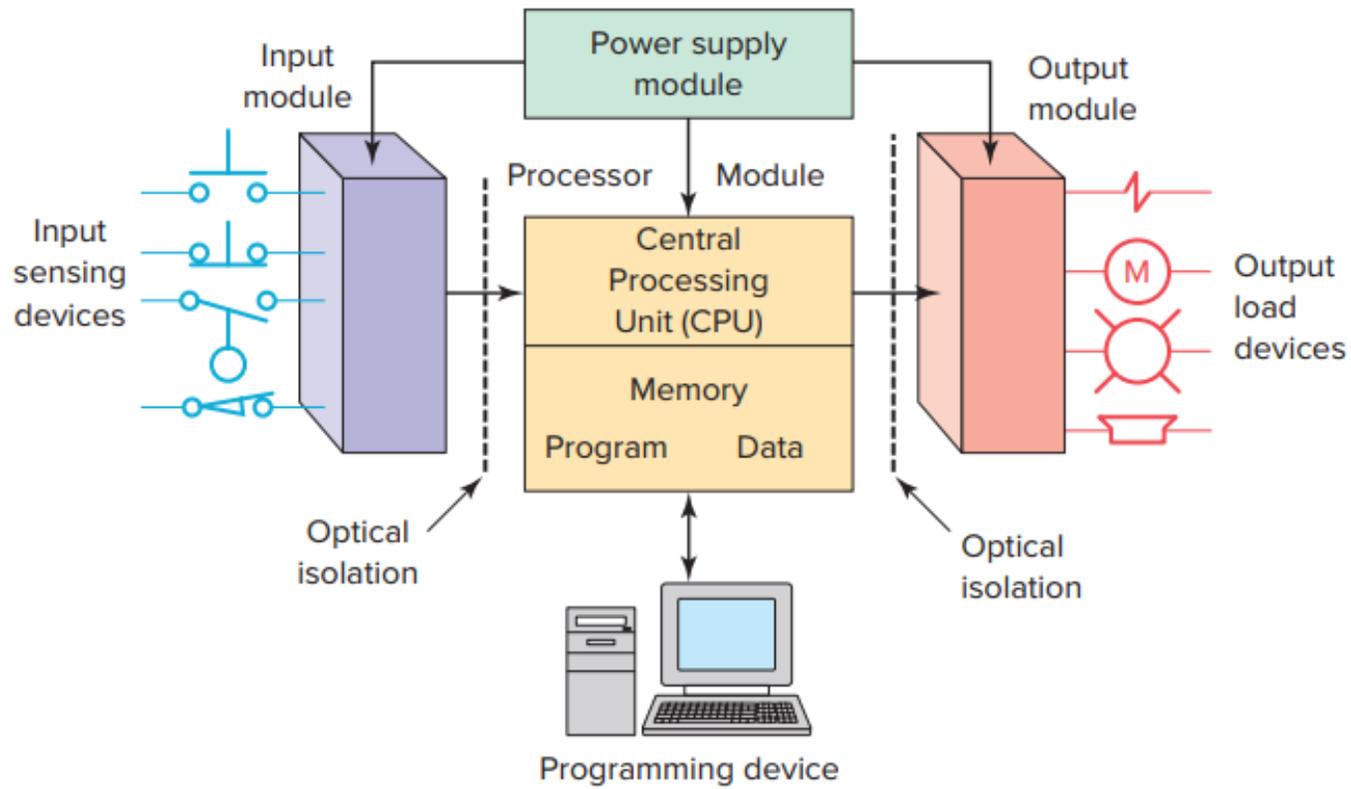
- Fixed I/O vs Modular I/O



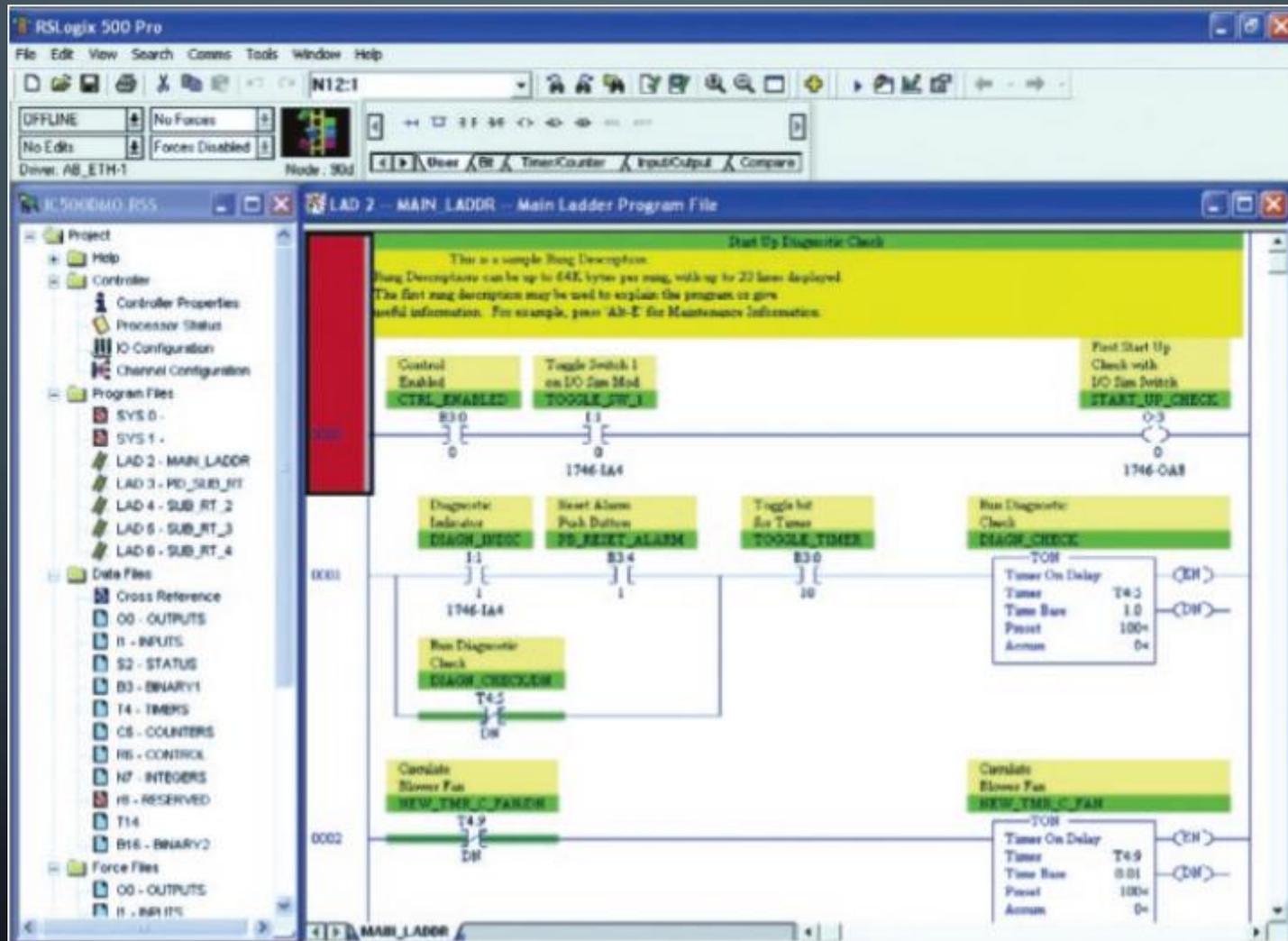
(b) Fixed type



# PARTS OF PLC

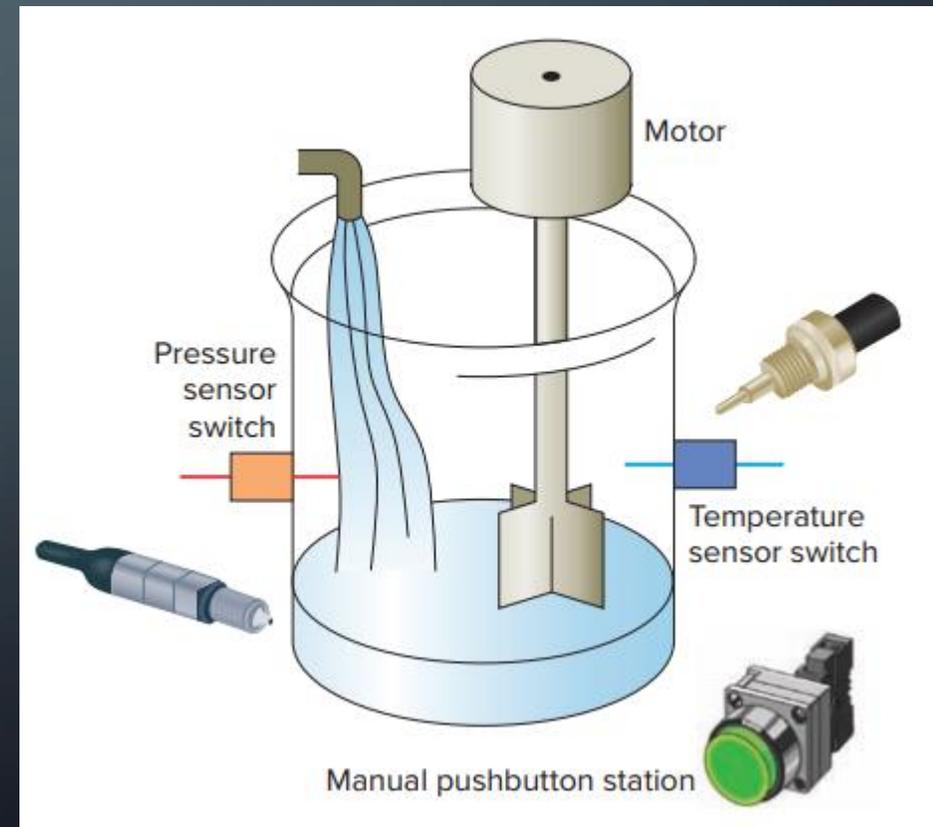
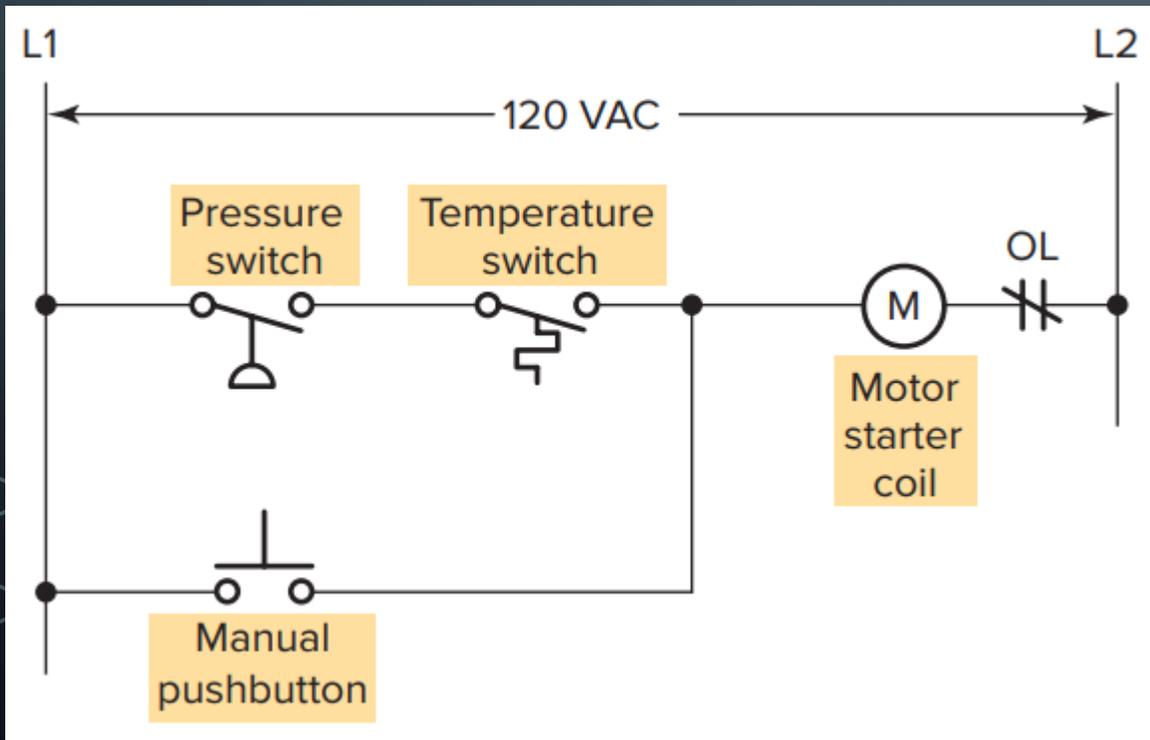


# PARTS OF PLC



# AN EXAMPLE

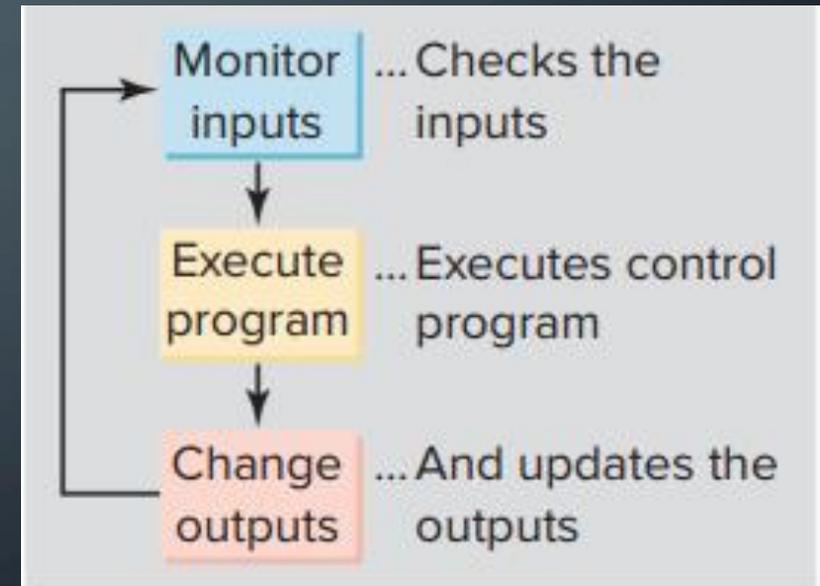
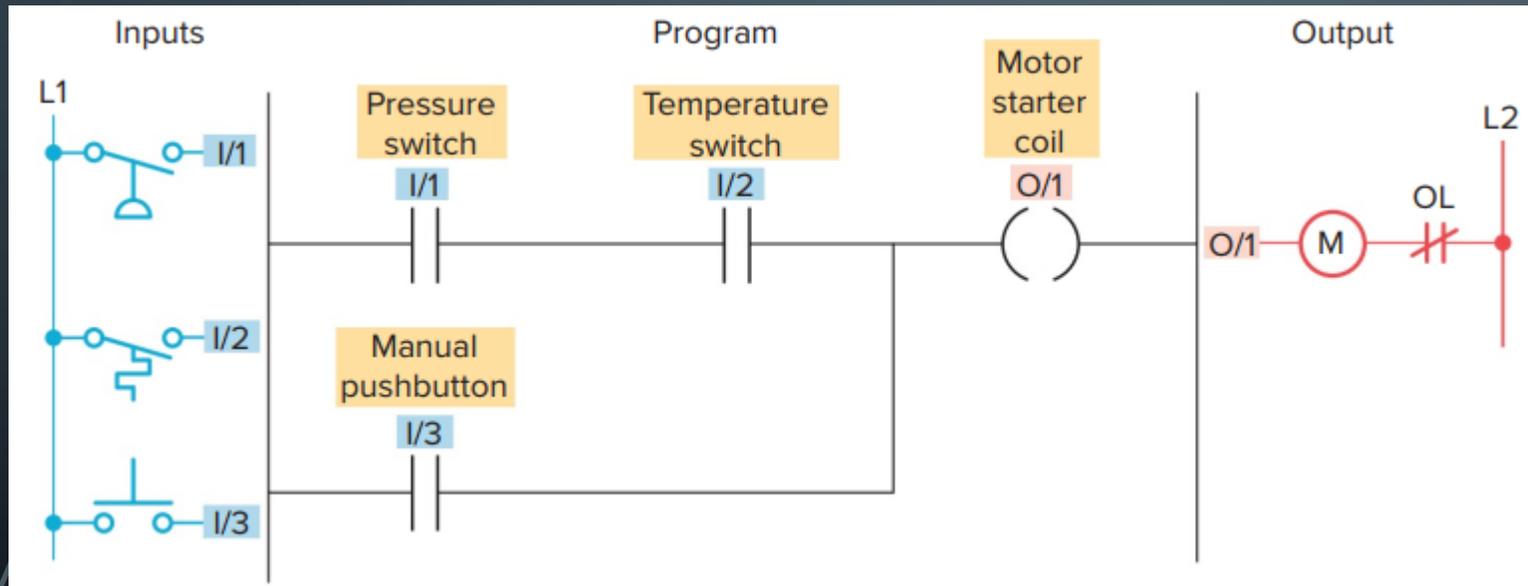
- Mixer process control: automatically stir the liquid in a vat when the temperature and pressure reach preset values



# AN EXAMPLE

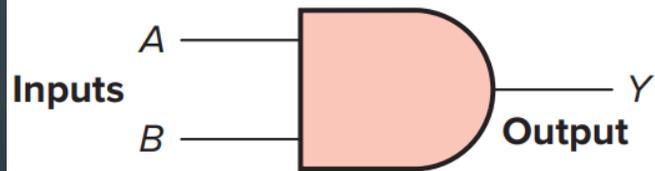


# AN EXAMPLE



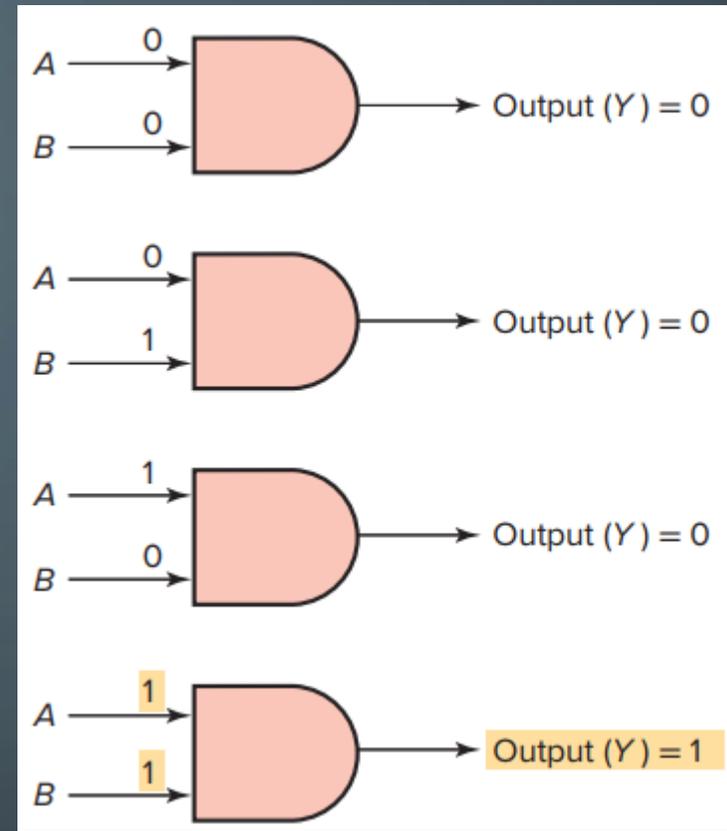
# FUNDAMENTALS OF LOGIC

- And Function

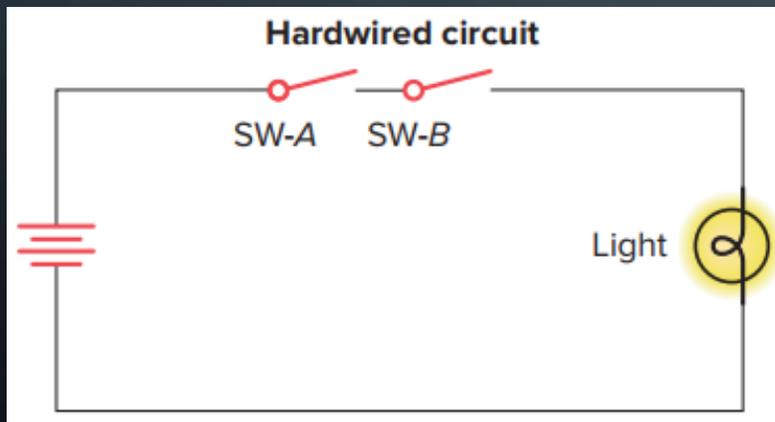


Two-input AND gate symbol

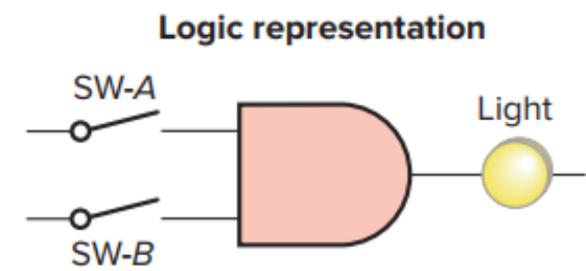
Inputs		Output
A	B	Y
0	0	0
0	1	0
1	0	0
1	1	1



A	B	Y
0	0	0
0	1	0
1	0	0
1	1	1

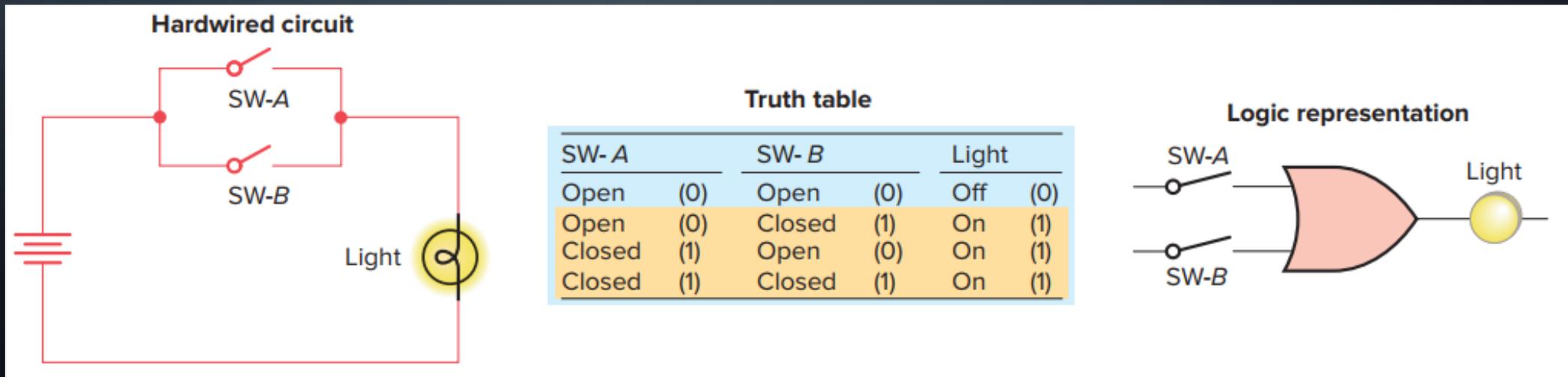
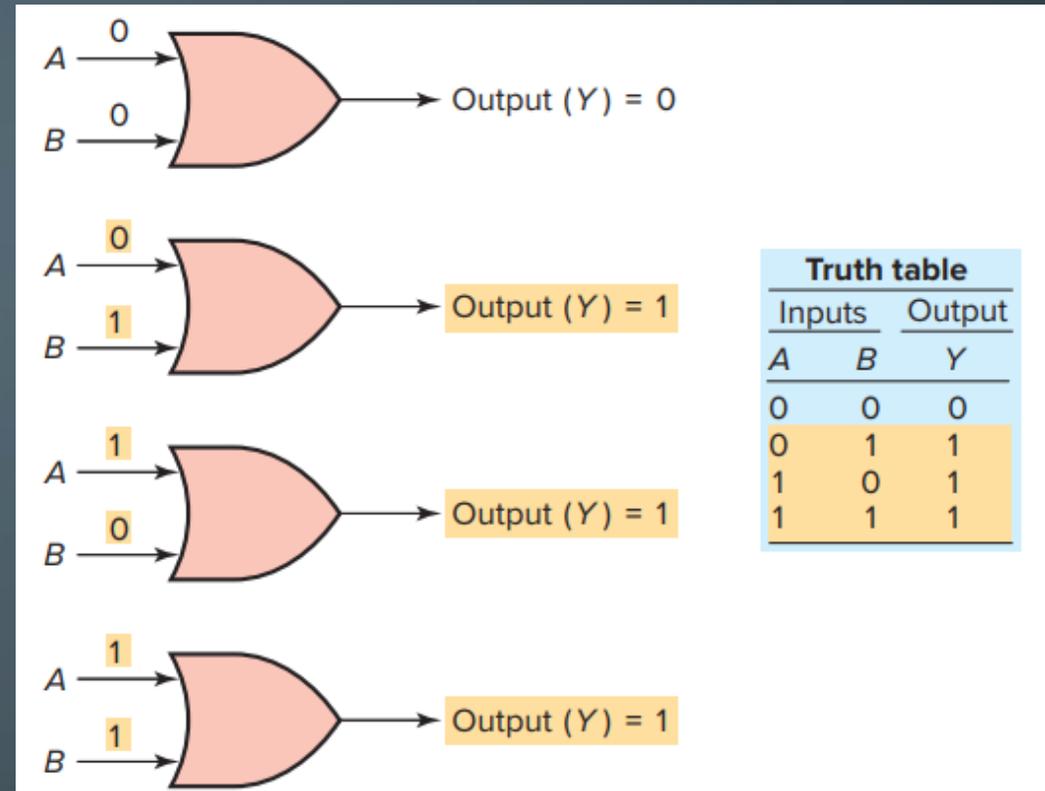
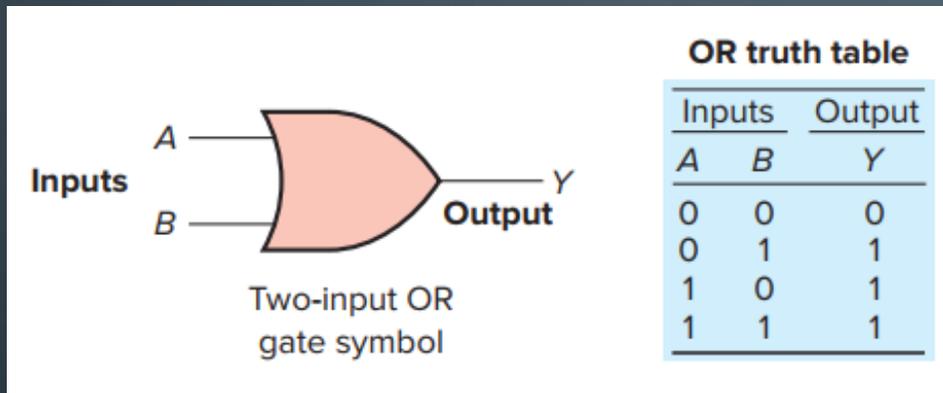


SW-A	SW-B	Light
Open (0)	Open (0)	Off (0)
Open (0)	Closed (1)	Off (0)
Closed (1)	Open (0)	Off (0)
Closed (1)	Closed (1)	On (1)



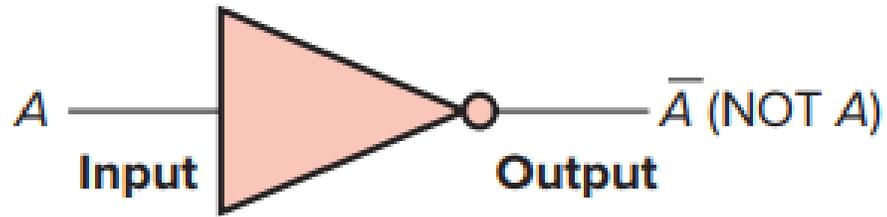
# FUNDAMENTALS OF LOGIC

- Or Function



# FUNDAMENTALS OF LOGIC

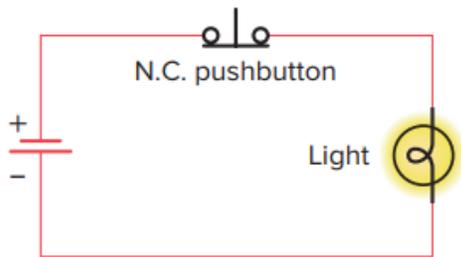
- Not Function



**NOT truth table**

A	NOT A
0	1
1	0

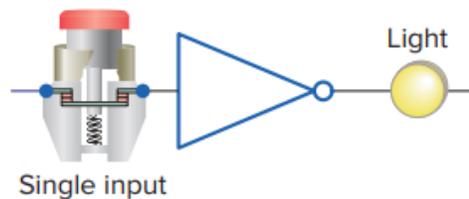
**Hardwired circuit**



**Truth table**

Pushbutton		Light
Not pressed	(0)	On (1)
Pressed	(1)	Off (0)

**Logic representation**

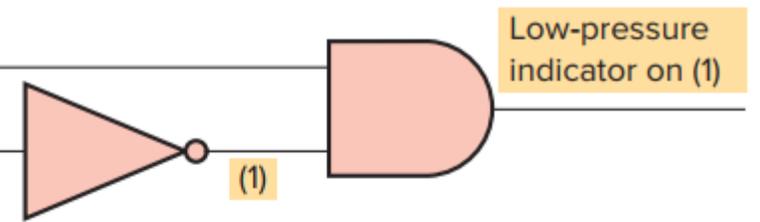


(Power on)

A = 1

B = 0

(Pressure switch open)



**Truth table**

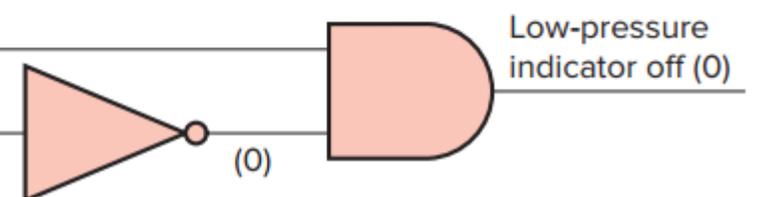
Pressure switch	Power	Pressure indicator
0	1	1
1	1	0

(Power on)

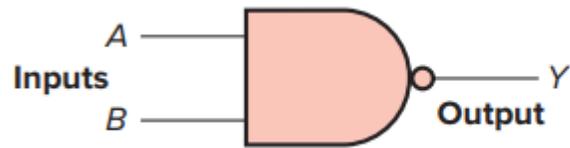
A = 1

B = 1

(Pressure switch closed)



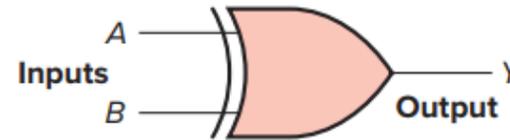
# FUNDAMENTALS OF LOGIC



Two-input  
NAND gate

NAND truth table

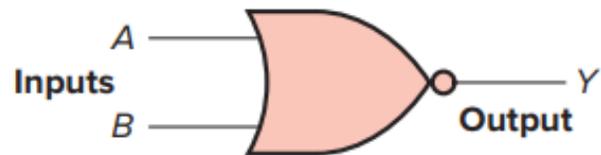
Inputs		Output
A	B	Y
0	0	1
0	1	1
1	0	1
1	1	0



Exclusive-OR

Truth table

Inputs		Output
A	B	Y
0	0	0
0	1	1
1	0	1
1	1	0

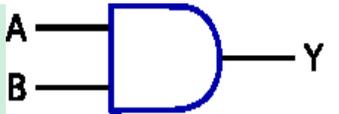
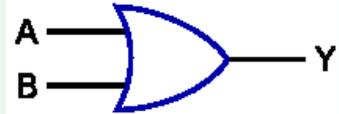
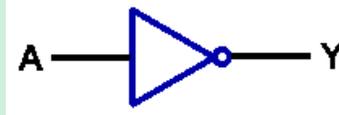


Two-input  
NOR gate

NOR truth table

Inputs		Output
A	B	Y
0	0	1
0	1	0
1	0	0
1	1	0

# BOOLEAN ALGEBRA

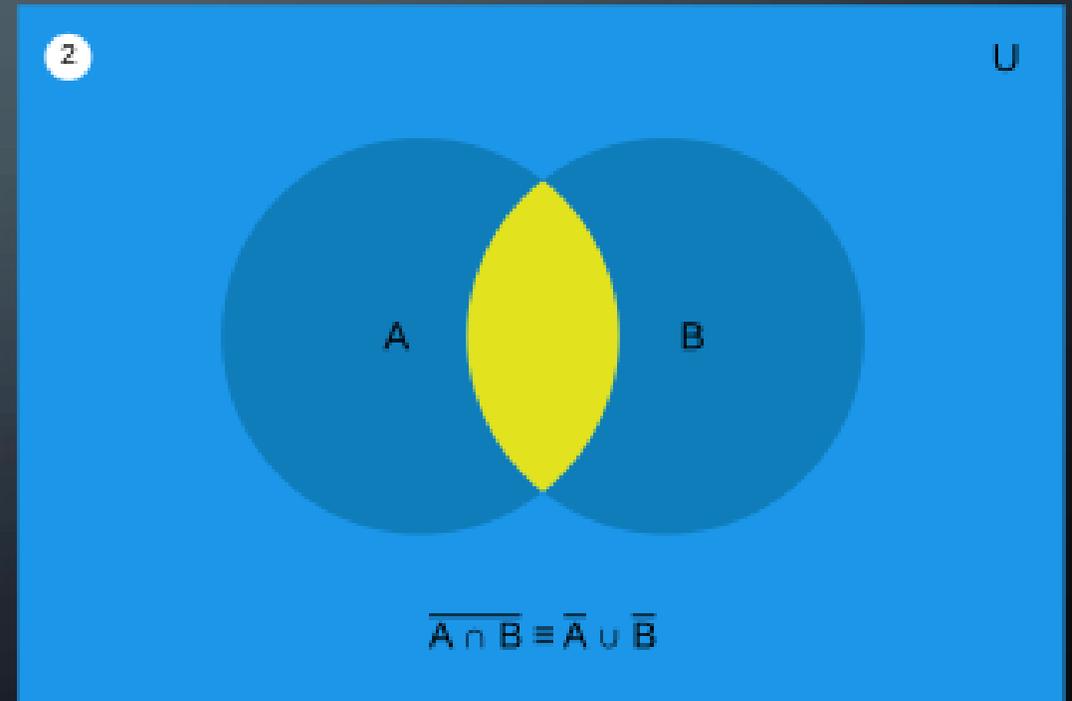
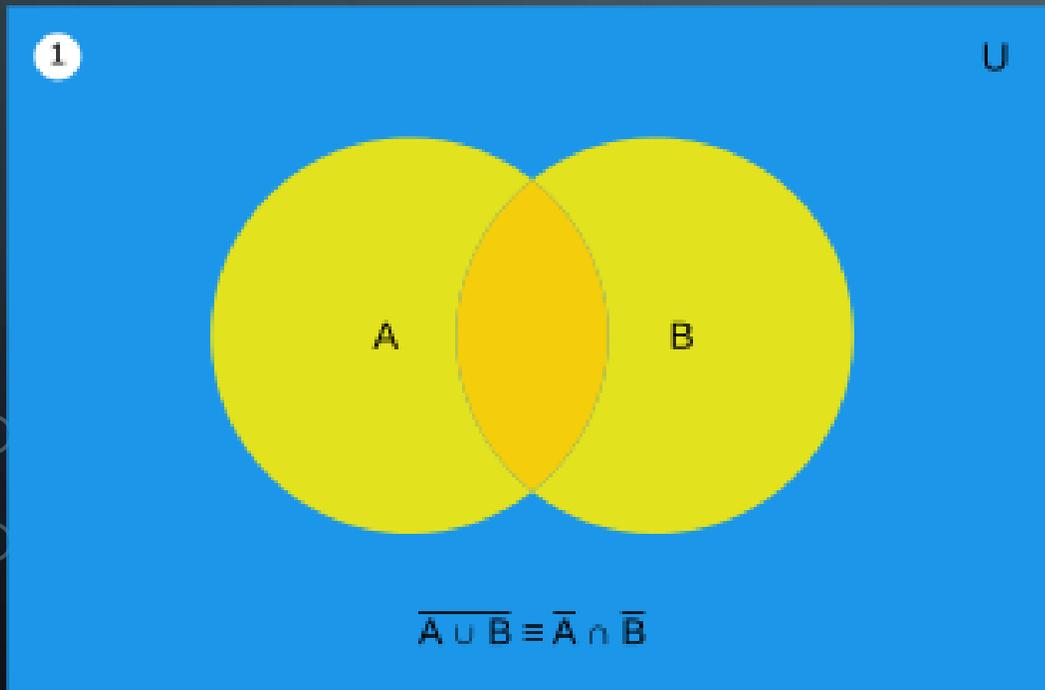
	Logic Gate	Set Theory	Binary Operations
Conjunction <b>AND</b>		Intersection, $\cap$ $A \cap B = Y$	$A \cdot B = Y$
Disjunction <b>OR</b>		Union, $\cup$ $A \cup B = Y$	$A + B = Y$
Negation <b>NOT</b>		Complement - $\bar{A} = Y$	$\sim A = Y$
Exclusive disjunction <b>XOR</b>		$(\bar{A} \cap B) \cup (A \cap \bar{B}) = Y$	$A \oplus B = Y$
Non-conjunction <b>NAND</b>		$\sim(A \cap B) = Y$	$\sim(A \cdot B) = Y$
Non-disjunction <b>NOR</b>		$\sim(A \cup B) = Y$	$\sim(A + B) = Y$

# PROPERTIES

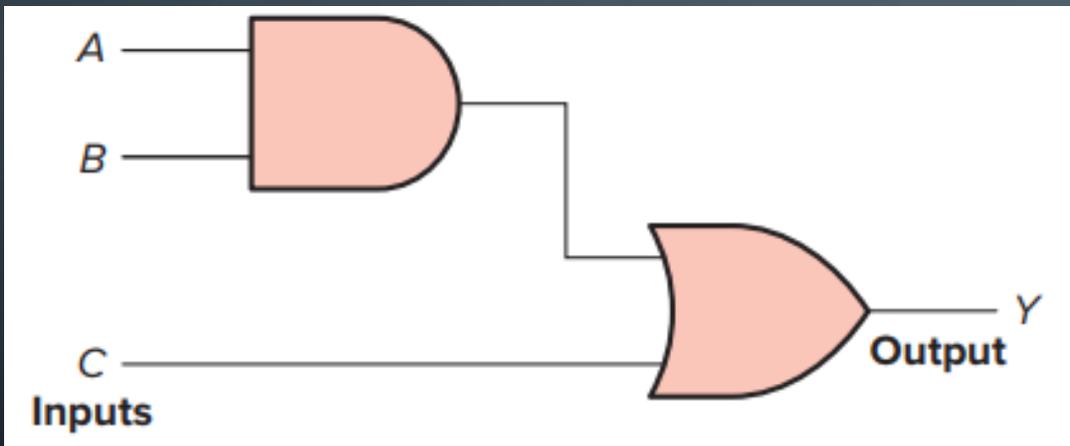
Associative property	$(A \cdot B) \cdot C = A \cdot (B \cdot C)$	$(A + B) + C = A + (B + C)$
Commutative property	$A \cdot B = B \cdot A$	$A + B = B + A$
Distributive property	$A \cdot (B + C) = A \cdot B + A \cdot C$	$A + (B \cdot C) = (A + B) \cdot (A + C)$
Identity	$A \cdot 1 = A$	$A + 0 = A$
Inverse	$A \cdot \sim A = 0$	$A + \sim A = 1$
Absorption	$A \cdot (A + B) = A$	$A + (A \cdot B) = A$
deMorgan's theorem	$\sim(A \cdot B) = \sim A + \sim B$	$\sim(A + B) = (\sim A) \cdot (\sim B)$

# DE MORGAN'S LAW

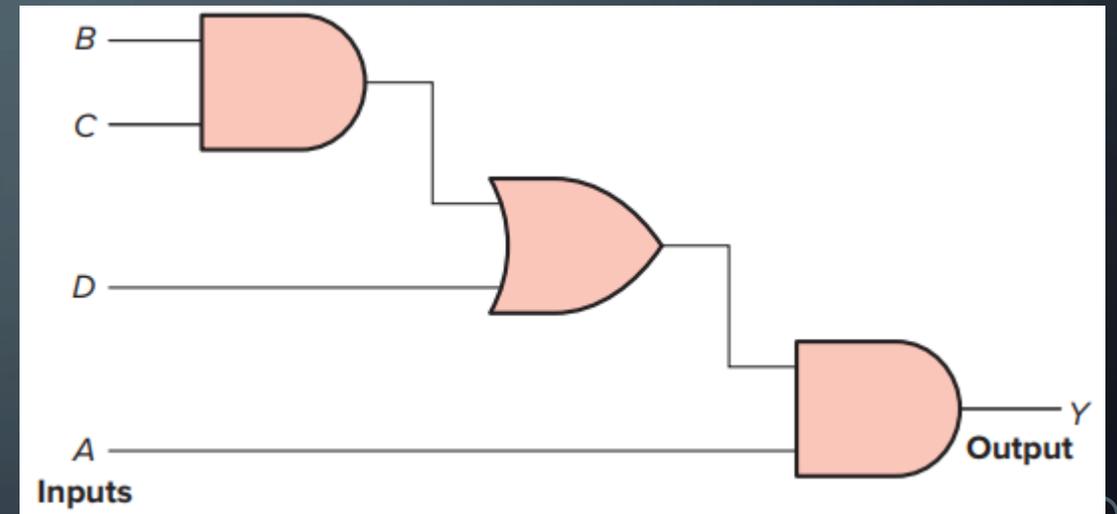
- the negation of a disjunction is the conjunction of the negations
- the negation of a conjunction is the disjunction of the negations



# LOGIC GATE CIRCUITS & BOOLEAN EQUATION

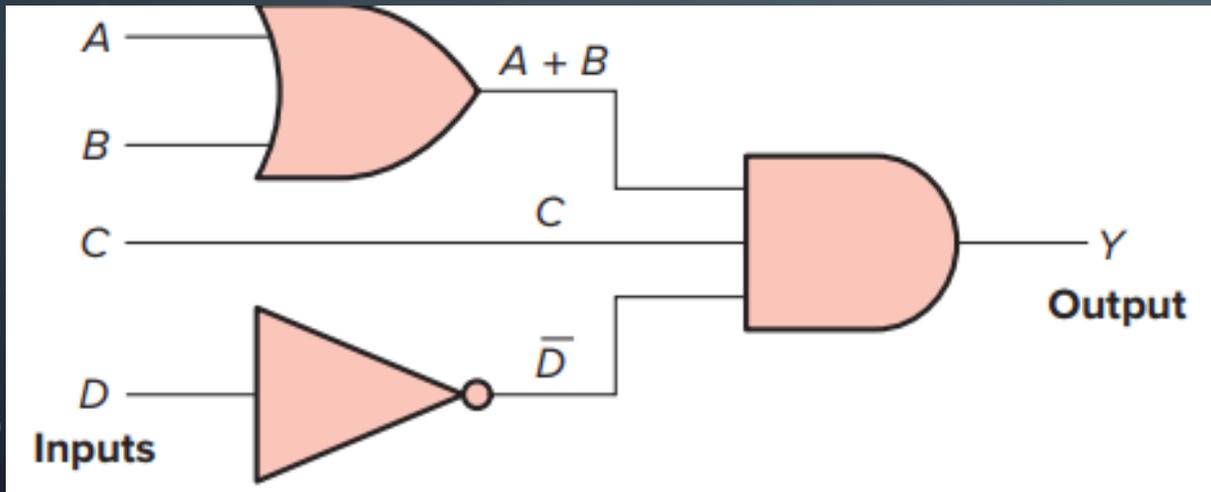


Boolean expression:  $Y = AB + C$

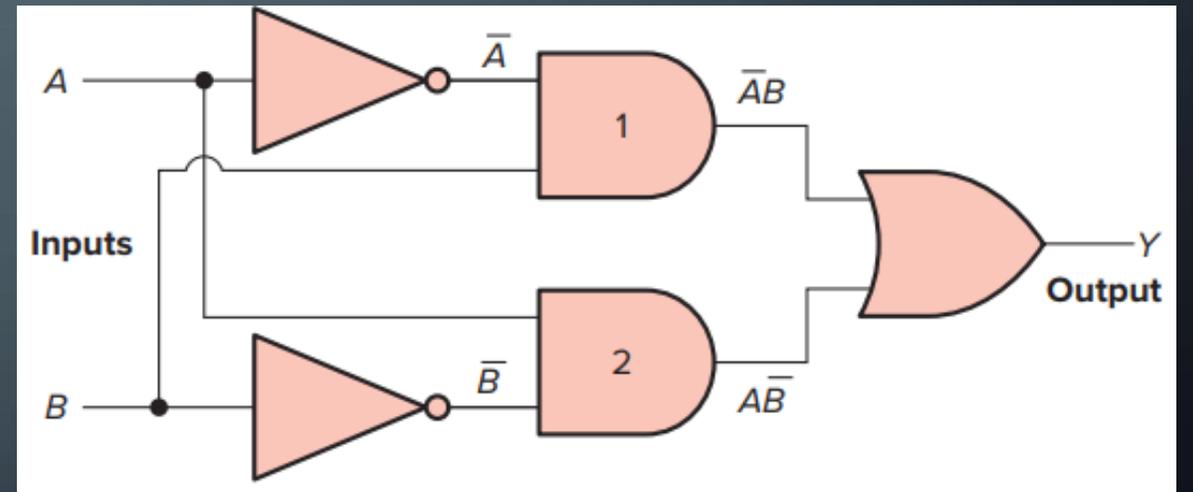


Boolean expression:  $Y = A(BC + D)$

# LOGIC GATE CIRCUITS & BOOLEAN EQUATION

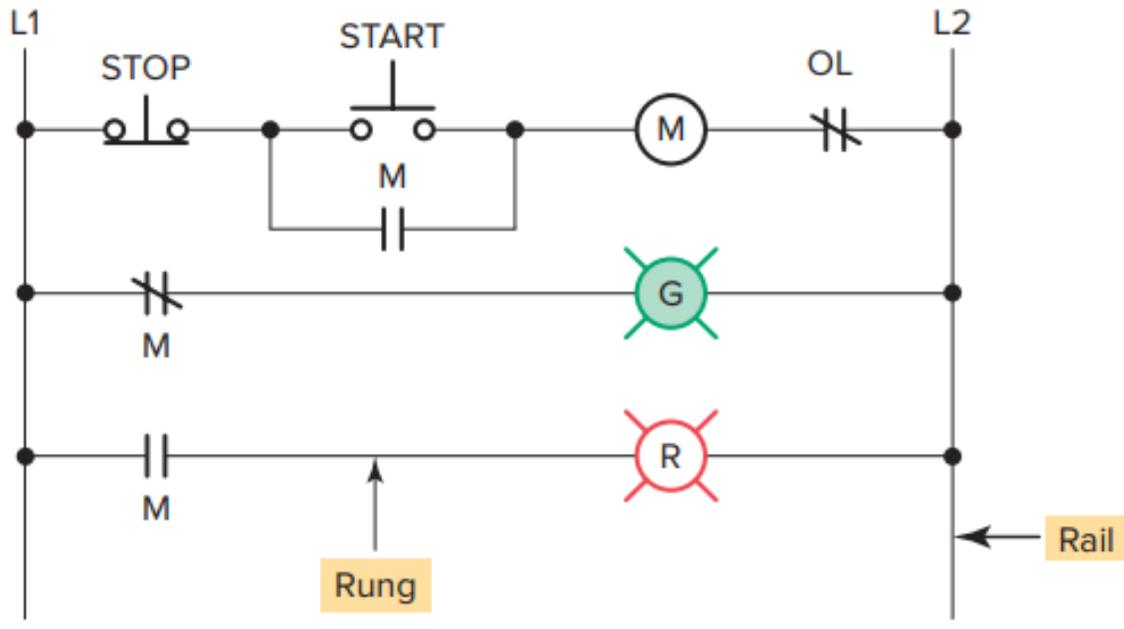


Boolean expression:  $Y = C\bar{D}(A + B)$

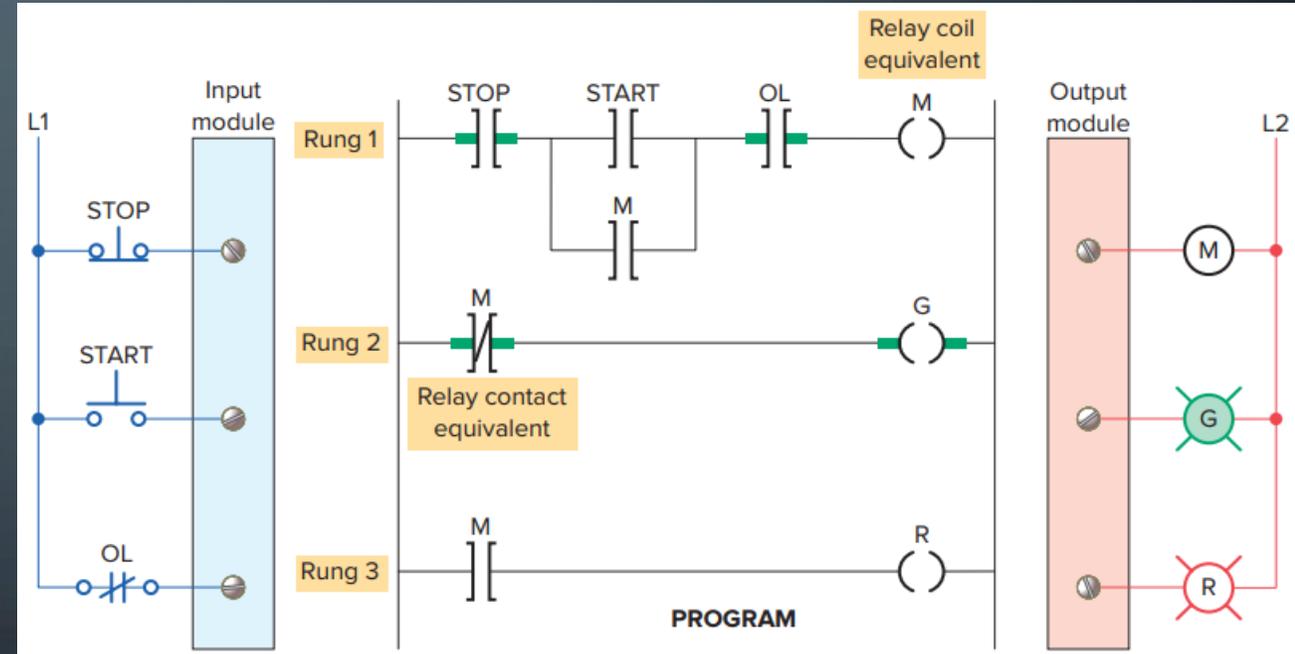


Boolean expression:  $Y = \bar{A}B + A\bar{B}$

# HARDWIRED LOGIC VS PROGRAMMED LOGIC

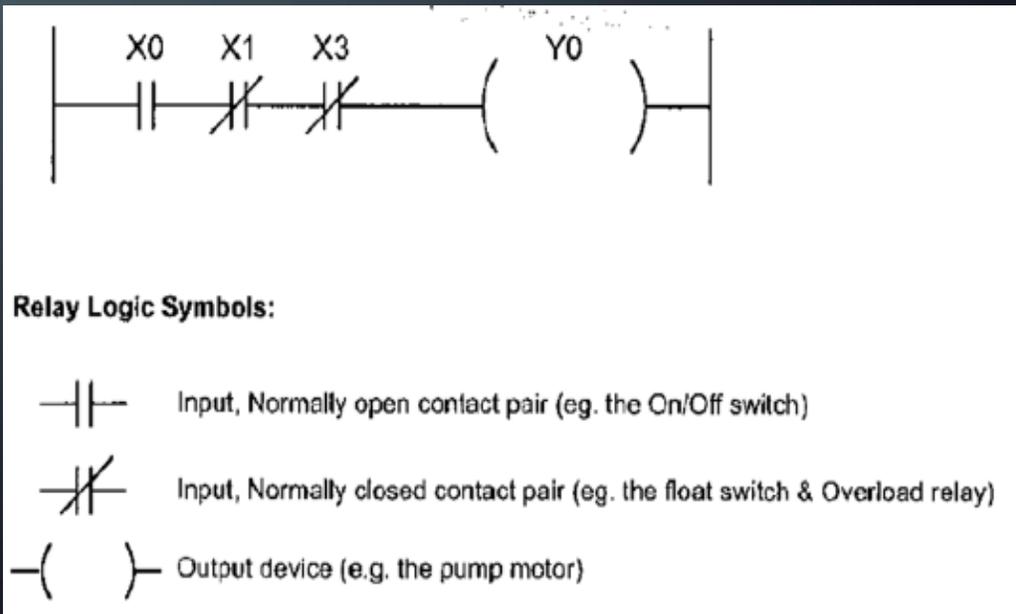
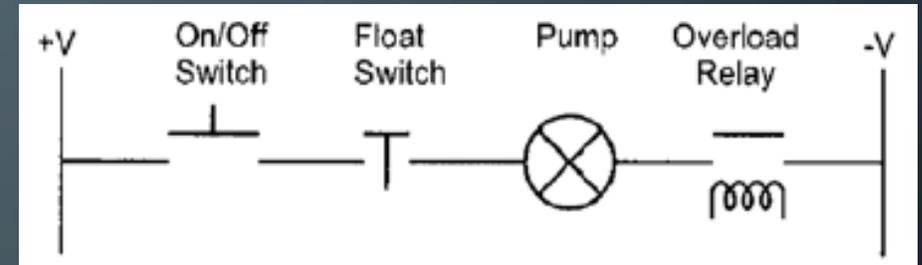
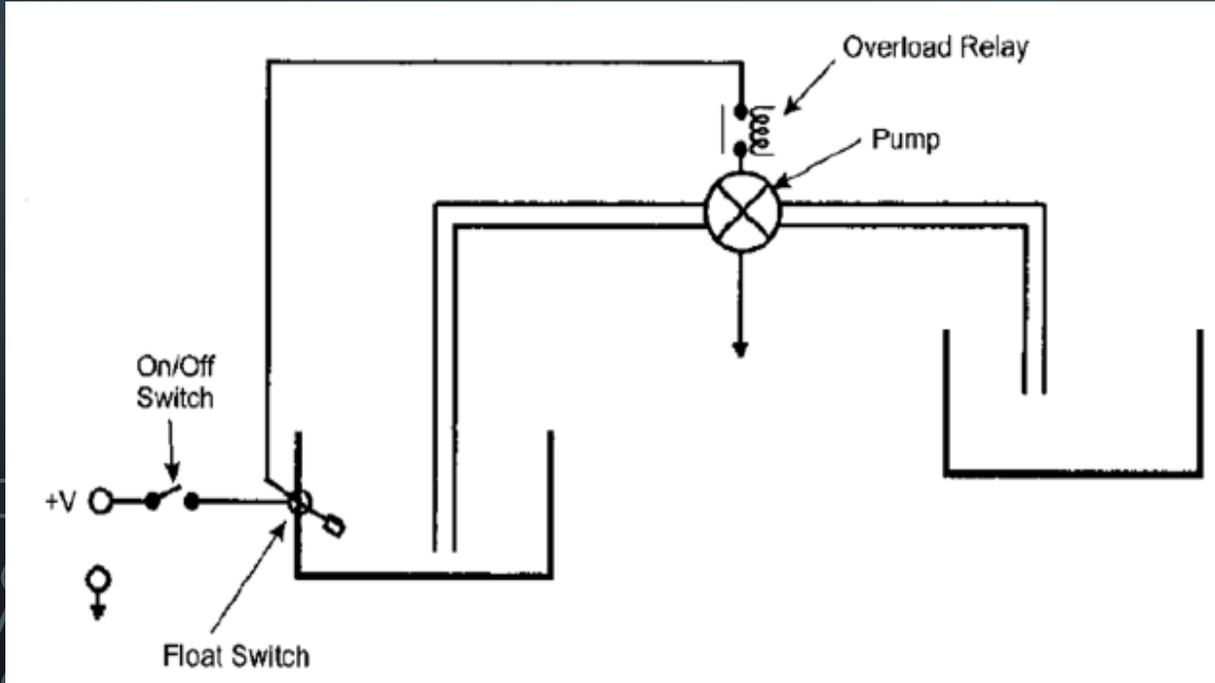


Motor stop/start relay ladder schematic

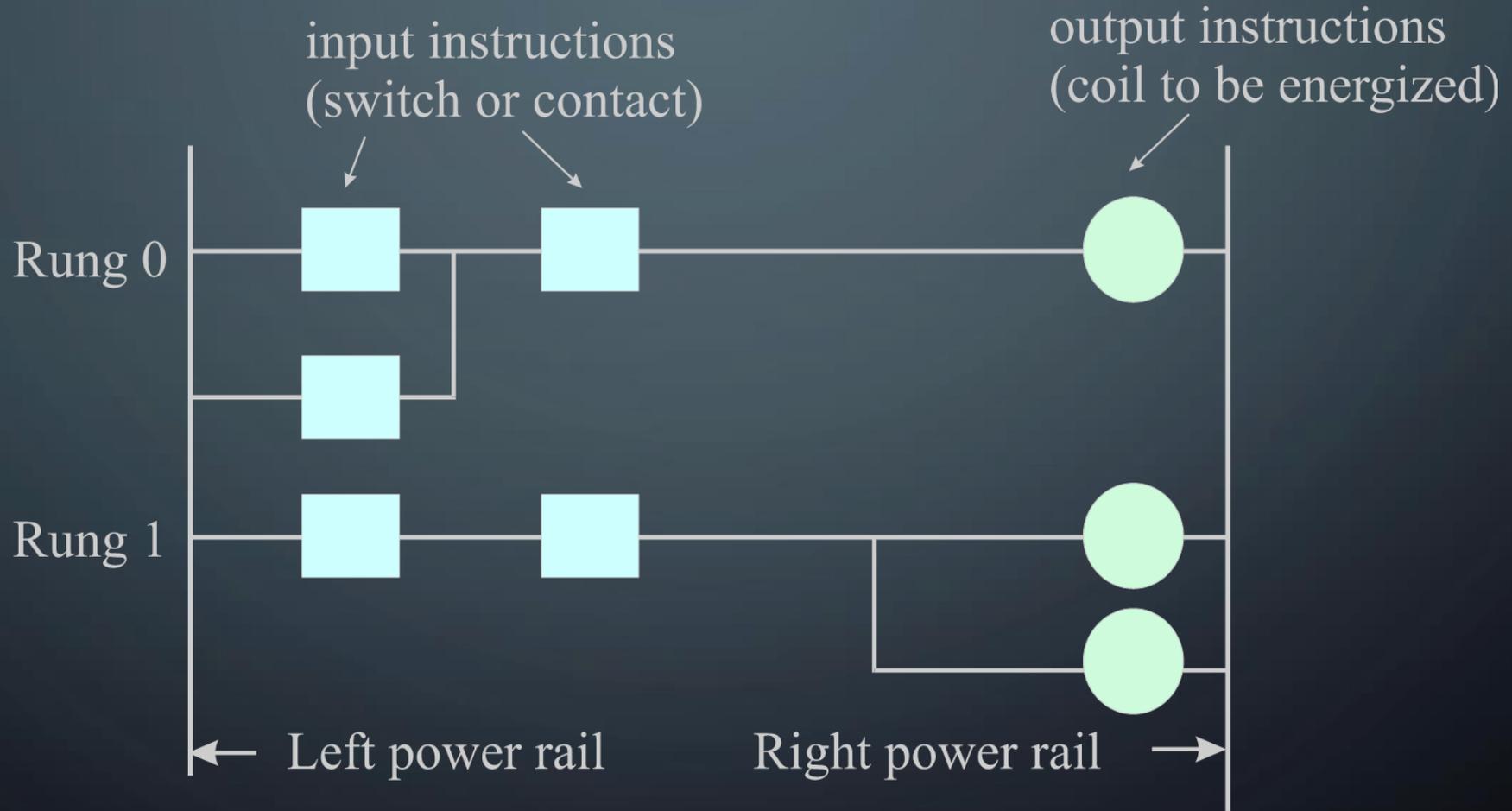


Motor stop/start ladder logic program

# HARDWIRED LOGIC VS PROGRAMMED LOGIC



# LADDER LOGIC



# LADDER LOGIC

- Ladder logic strongly resembles a schematic diagram of relay logic.
- Ladder logic notation is chosen to reduce training demands for the existing technicians.
- Input instructions are entered on the left (left power rail).
- Output instructions are entered on the right.
- The output will execute only if the connection is made from left to right power rail.
- The program is executed from top to bottom, left to right.

# LADDER LOGIC

- There are both *contacts* and *coils* that can be loaded and driven in different configurations that make up a ladder diagram.
- Devices are actuated by or act upon variables associated with the PLC hardware.
- All the variables are **logical**, and take values either OFF (Logical '0') or ON (Logical '1').

Instruction	Symbol
Contact (Normally Open)	
Contact (Normally Closed)	
Coil	

X	This is used to represent the physical inputs to the PLC. There are 8 physical inputs to the CE123 addressed as X0 — X7
Y	This represents the physical outputs of the PLC. There are 6 physical outputs to the CE123 addressed as Y0 – Y5
T	This represents a timing device in the PLC. There are 64 timers in the CE123 addressed as T0 to T63. The CE123 timers are set in units of 0.1 seconds but can be reprogrammed. Timers and counters will be further discussed below
C	This represents a counting device in the PLC. There are 32 counters in the CE123 addressed as C0-C31
M	These are used to represent internal operational flags in the PLC. There are 512 M flags.

# Ladder Logic For Basic gates

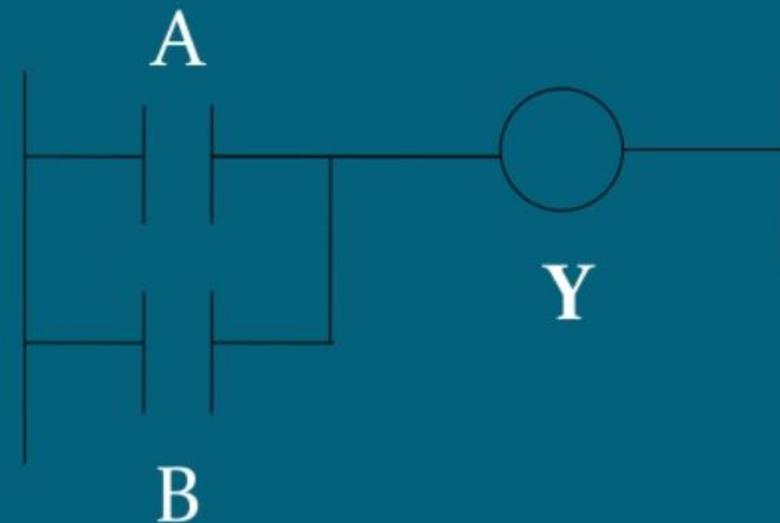
## AND Gate

A	B	Logic(Y)
OFF	OFF	OFF
OFF	ON	OFF
ON	OFF	OFF
ON	ON	ON



## OR Gate

A	B	Logic(Y)
OFF	OFF	OFF
OFF	ON	ON
ON	OFF	ON
ON	ON	ON



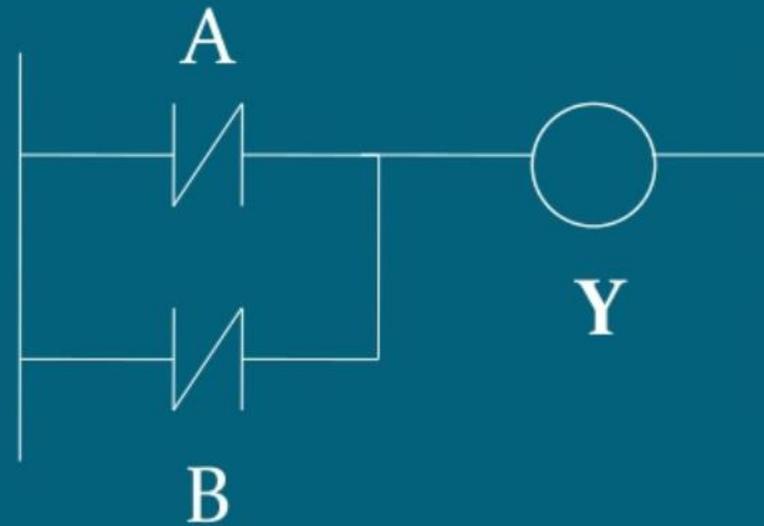
## NOR Gate

A	B	Logic(Y)
OFF	OFF	ON
OFF	ON	OFF
ON	OFF	OFF
ON	ON	OFF

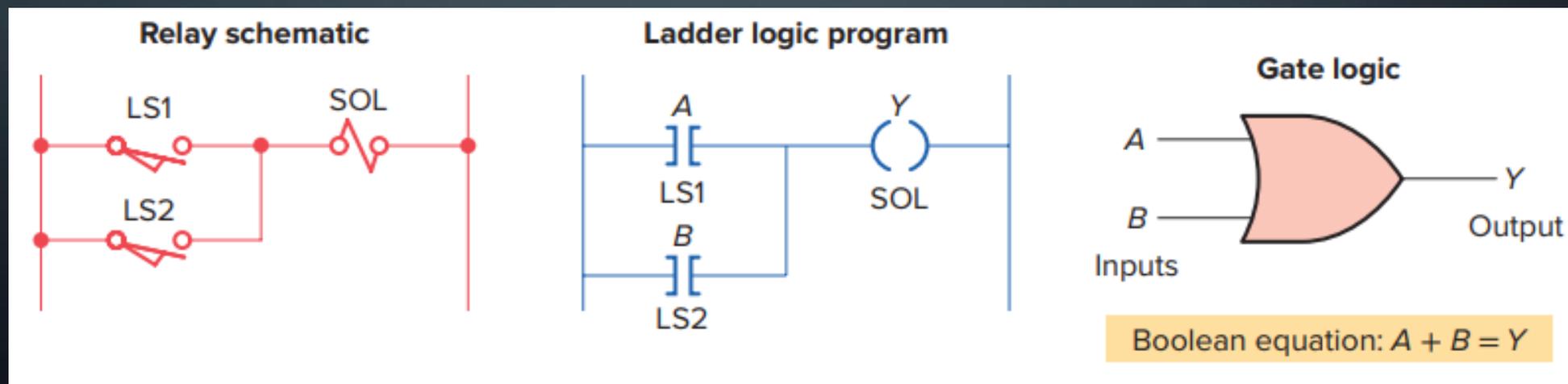
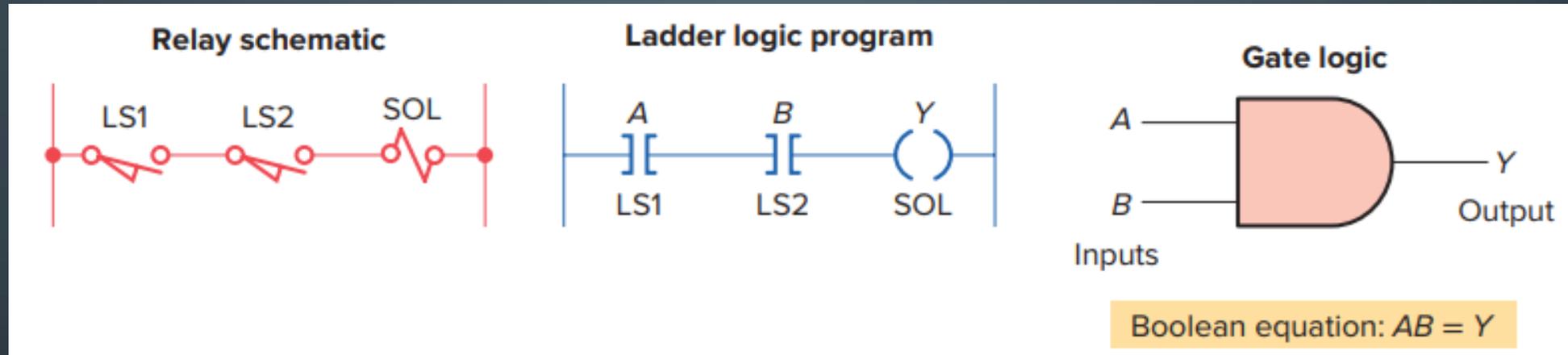


## NAND Gate

A	B	Logic(Y)
OFF	OFF	ON
OFF	ON	ON
ON	OFF	ON
ON	ON	OFF

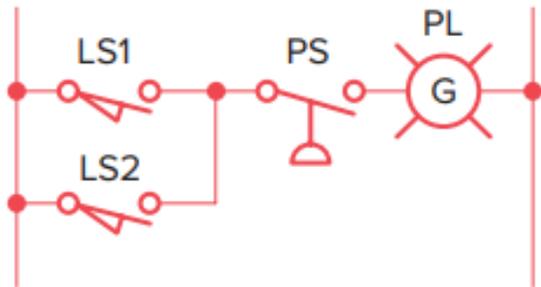


# SAMPLE LADDER LOGIC PROGRAM

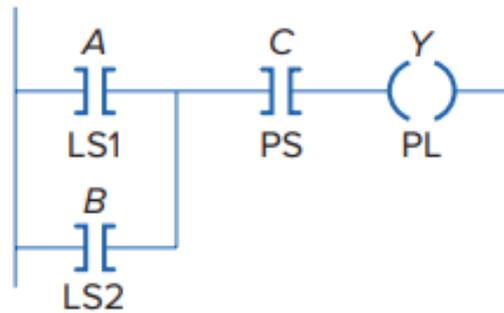


# SAMPLE LADDER LOGIC PROGRAM

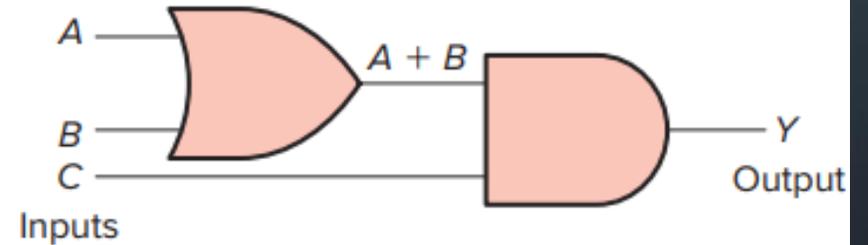
Relay schematic



Ladder logic program

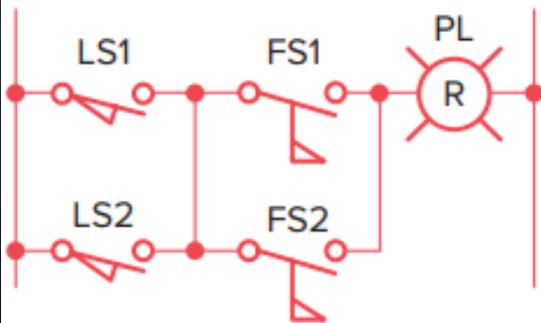


Gate logic

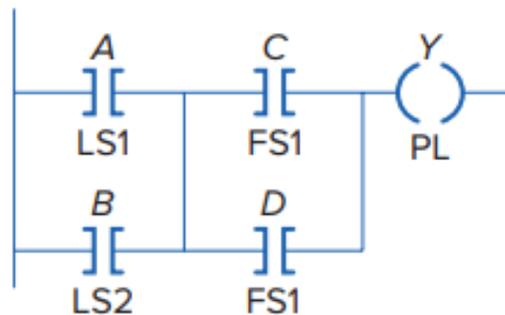


Boolean equation:  $(A + B)C = Y$

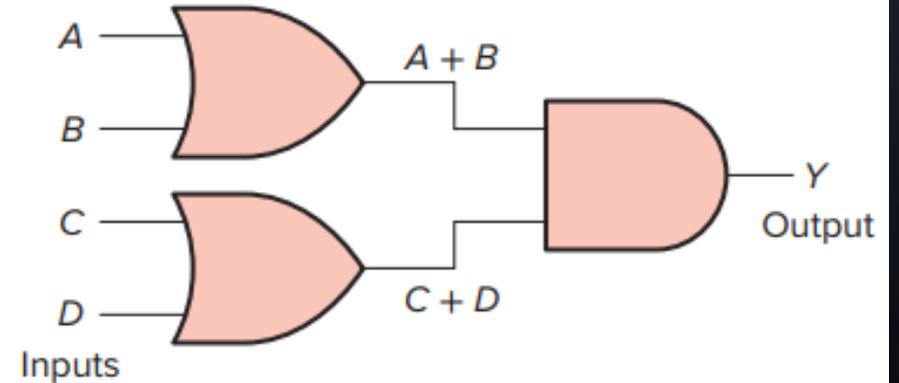
Relay schematic



Ladder logic program



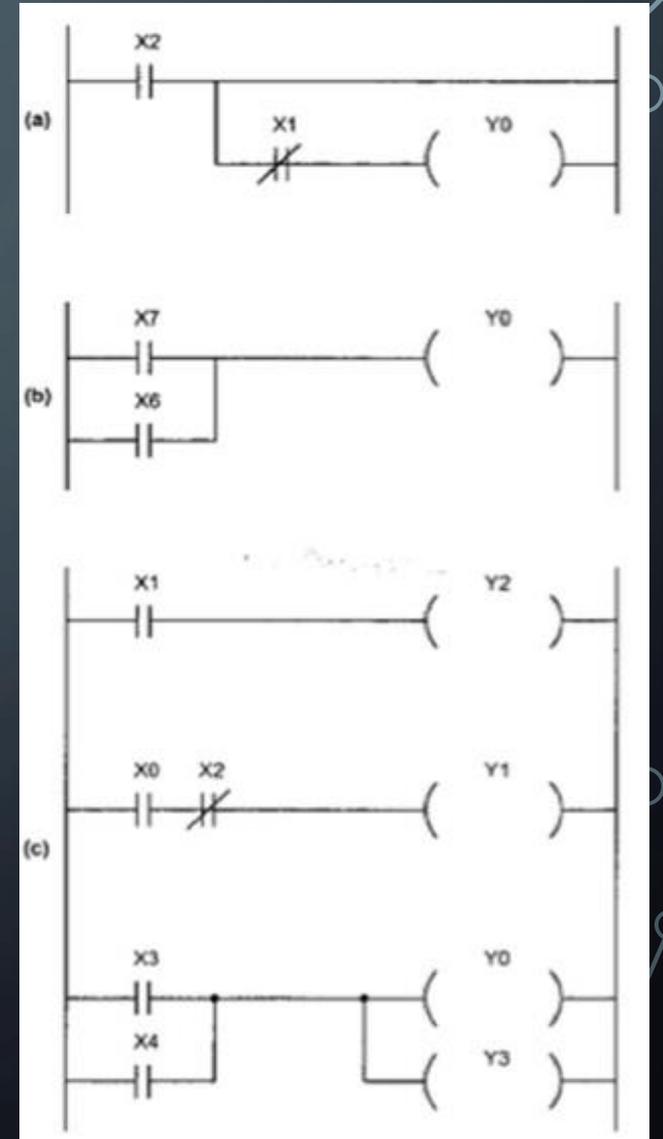
Gate logic



Boolean equation:  $(A + B)(C + D) = Y$

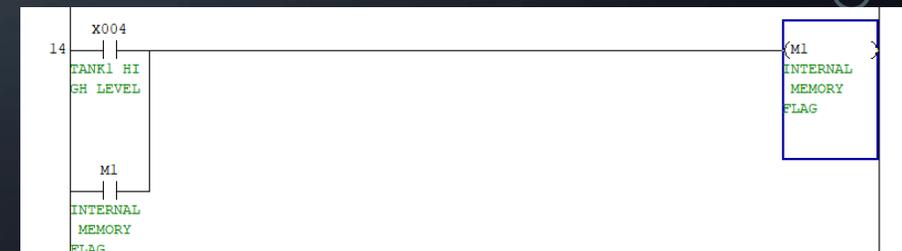
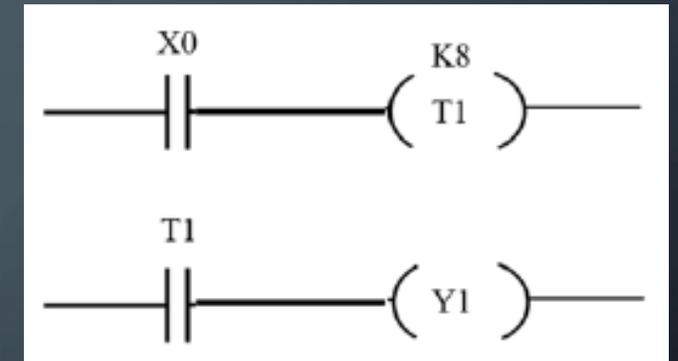
# LADDER LOGIC EXAMPLE

- (a) Represents a system comprised of a motor, Y0, which will only operate if switch X2 (normally open) has been closed and switch X1 (normally closed) has not been triggered.
- (b) Represents a system comprised of an output device, Y0, which will operate if either of two normally open switches, X6 or X7, are closed.
- (c) Shows a more complex diagram: output Y2 will be turned on if the contact, X1, is closed. Output Y1 is controlled by the state of witches X0 and X2, only being activated if X0 is closed and X2 is not opened. Outputs Y0 and Y3 will both be activated if either switch, X3 or X4 are closed.



# TIMERS AND FLAGS

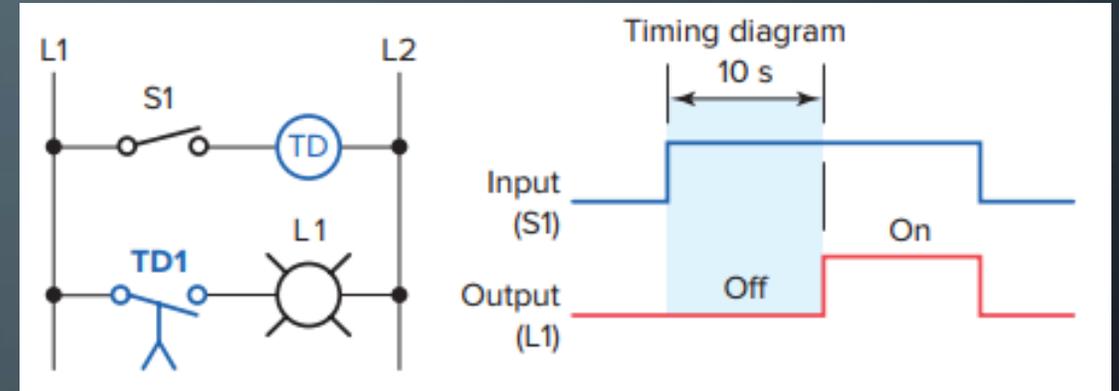
- Timers and Flags can be used to drive an output (coil) or they can be used to trigger an input (contact).
- When configuring a coil (output) for use as a timer, a constant must also be entered. This constant, identified by the letter “K”, tells the program how long that timer will run.
- If you enter K8 for a timer constant, the duration data will be held for 800 ms (8 x 100ms) or 0.8 seconds.
- When input X0 is opened, T1 is initiated and holds for 0.8 seconds before executing (opening). After 0.8 seconds, output Y1 is triggered.
- The number next to the M is used only as identification. Instead of writing the same code (which may be many lines long) you can store that line as a flag and call it when needed.



# TIMERS

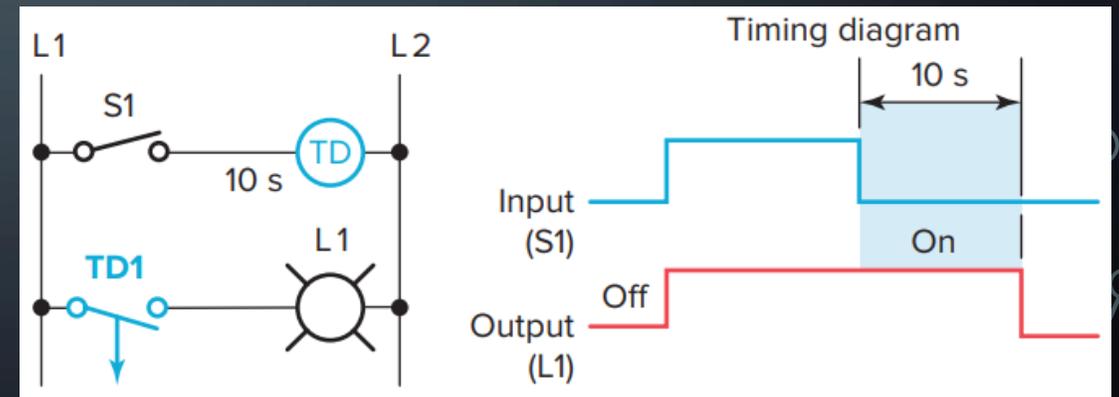
- **ON delay timer**

- When the input to an ON DELAY goes from false to true, the output goes to true after delaying a preset time interval (called TON)
- When the input to an ON DELAY goes from true to false, the output immediately goes to false.



- **OFF delay timer**

- When the input to an OFF DELAY goes from true to false, the output goes to false after delaying a preset time interval (called TOFF).
- When the input to an OFF DELAY goes from false to true, the output immediately goes to true.



# LAB 3 PLC

- Goal: To investigate the fundamentals of programmable logic controllers (PLCs) and their operation as it relates to fluid transport and liquid level
- Examine the time it takes to drain tank 1 to a specific level



# TIMER CONSTANT CALCULATION

- Torricelli's theorem

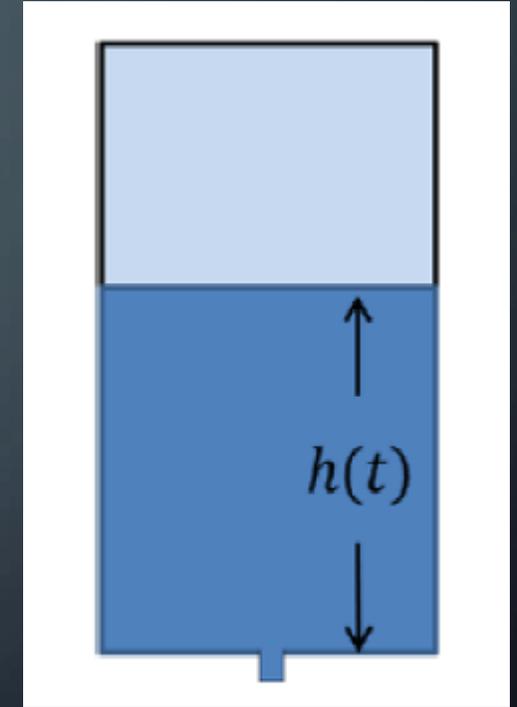
$$V = \sqrt{2gh}$$

- Conservation of mass

$$\frac{\delta m_{cv}}{\delta t} + \dot{m}_{out} = 0$$

- Exit mass flow rate

$$\dot{m}_{out} = \rho V A_o$$



# TIMER CONSTANT CALCULATION

- Rewrite the equation

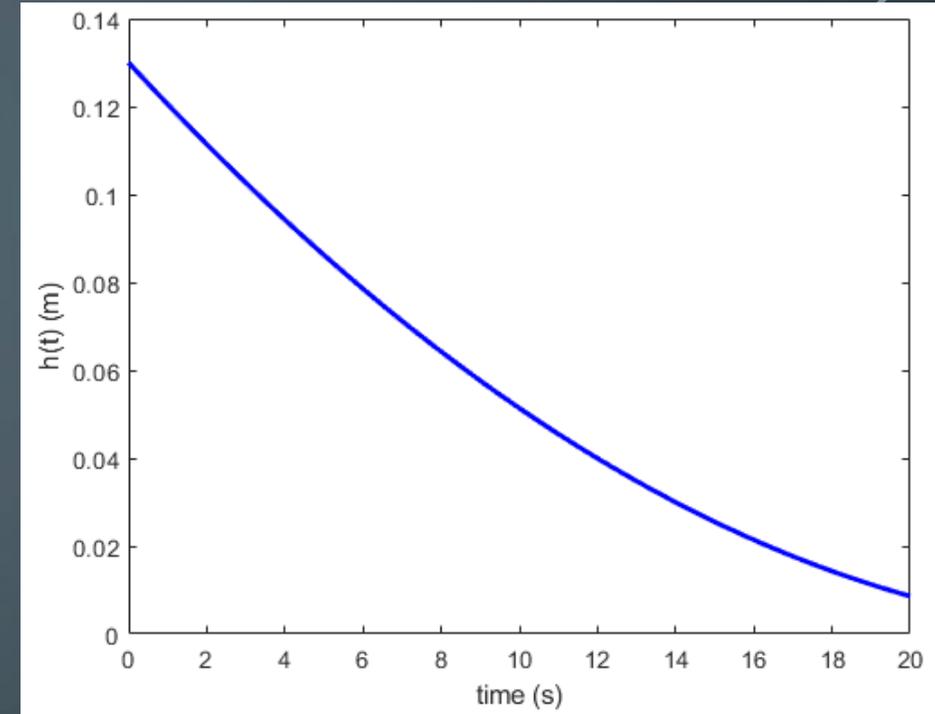
$$m_{cv} = \rho A_t h$$
$$\rho A_t \frac{dh}{dt} + \rho A_o \sqrt{2gh} = 0$$

- Separate variables and integrate

$$A_t \frac{dh}{\sqrt{h}} = -A_o \sqrt{2g} dt$$
$$2A_t (\sqrt{h(t)} - \sqrt{h(0)}) = -A_o \sqrt{2g} t$$
$$\sqrt{h(t)} = \sqrt{h(0)} - \frac{A_o}{A_t} \sqrt{\frac{g}{2}} t$$

# TIMER CONSTANT CALCULATION

- Tank Diameter: 90mm
- Outlet Diameter: 7mm
- Tank Height (Max Fluid Height): 130mm

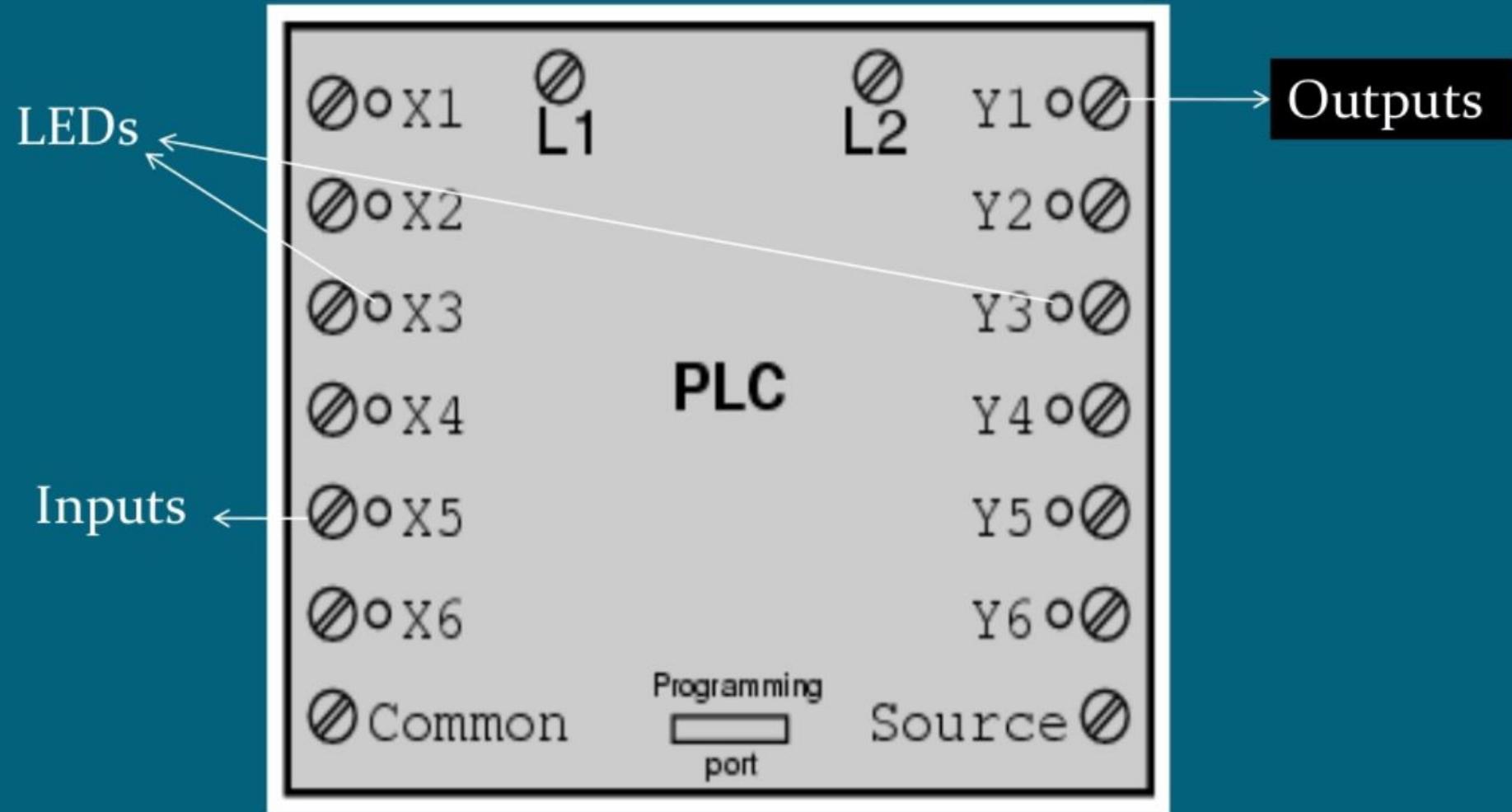


$$\sqrt{h(t)} = \sqrt{0.13} - \frac{0.007^2}{0.09^2} \sqrt{\frac{9.8}{2}} t$$
$$h(t) = (0.36 - 0.0134t)^2$$

# GX DEVELOPER SOFTWARE

- The menu driven software package supplied with the CE123 allows you to:
  - Create and edit ladder diagrams
  - Download and upload ladder diagrams to and from the PLC
  - Load and save ladder diagrams to and from disk
  - Add comments to aid ladder diagram clarity
  - Monitor ladder diagrams in the PLC
  - Print ladder diagrams and comments
- Operation of the GX developer software will be investigated in the Studio Assignment.

# Block diagram of a PLC



Socket Label	I/O	Function
L1	Output	Tank 2 LOW level Switch
L2	Output	Tank 2 HIGH level Switch
L3	Output	Tank 1 LOW level Switch
L4	Output	Tank 1 HIGH level Switch
L5	Output	Reservoir LOW level Float Switch
V1	Input	Pump to Reservoir Valve (by-pass)
V2	Input	Tank 1 Feed Valve
V3	Input	Tank 1 Drain Valve
V4	Input	Tank 2 Drain Valve
P1	Input	Pump ON/OFF
F1	Output	Flow meter, pulse related to flow rate

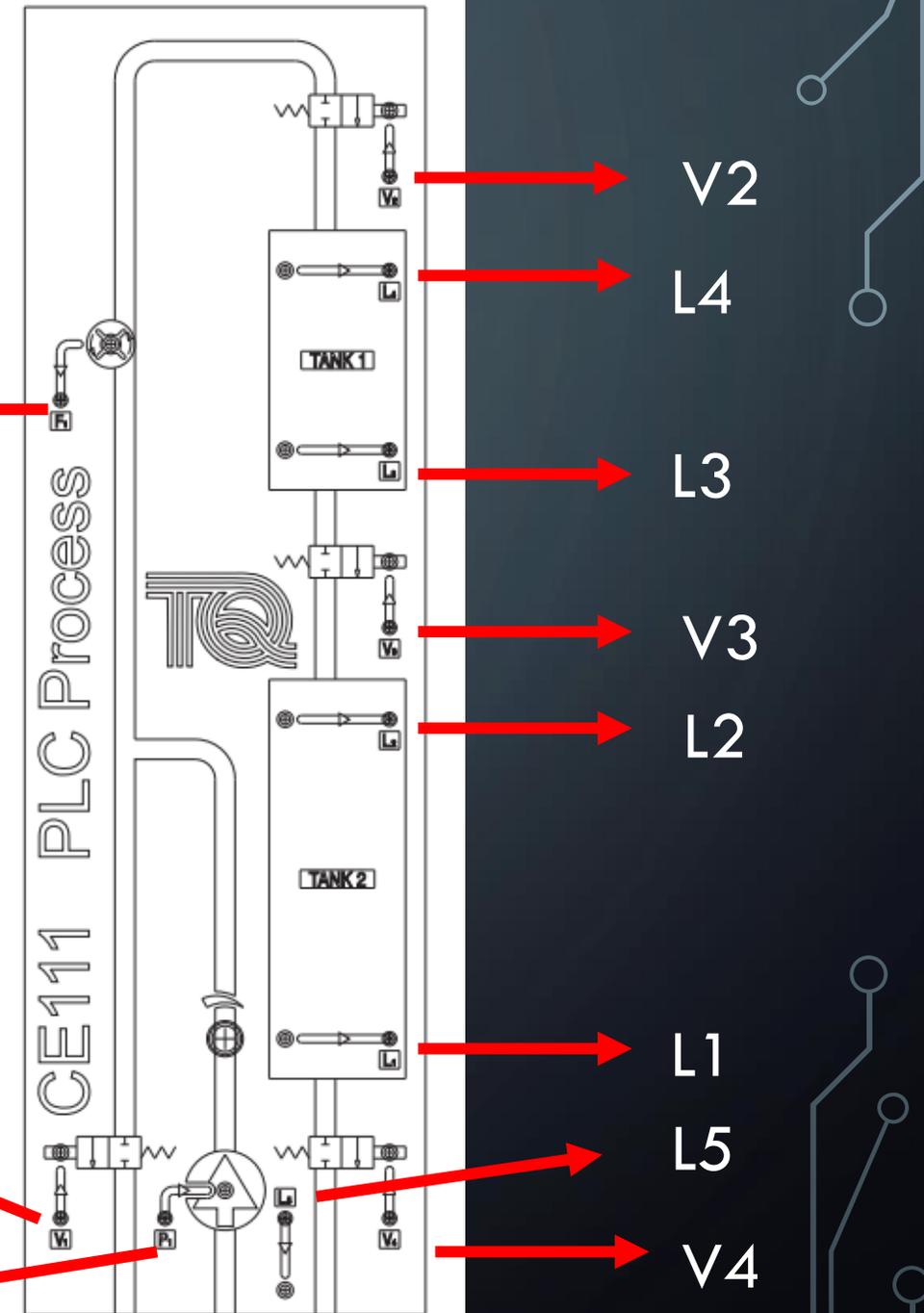
F1

**Table 2.1:** Connection of Inputs/Outputs between CE111 and CE123

CE111	CE123	Function
L1	X1	Tank 2 LOW level Float Switch
L2	X2	Tank 2 HIGH level Float Switch
L3	X3	Tank 1 LOW level Float Switch
L4	X4	Tank 1 HIGH level Float Switch
L5	X5	Reservoir LOW level Float Switch
V1	Y1	Pump to Reservoir Valve (by-pass)
V2	Y2	Tank 1 Feed Valve
V3	Y3	Tank 1 Drain Valve
V4	Y4	Tank 2 Drain Valve
P1	Y0	Pump ON/OFF
F1	X0	Flow meter, pulse related to flow rate

V1

P1



V2

L4

L3

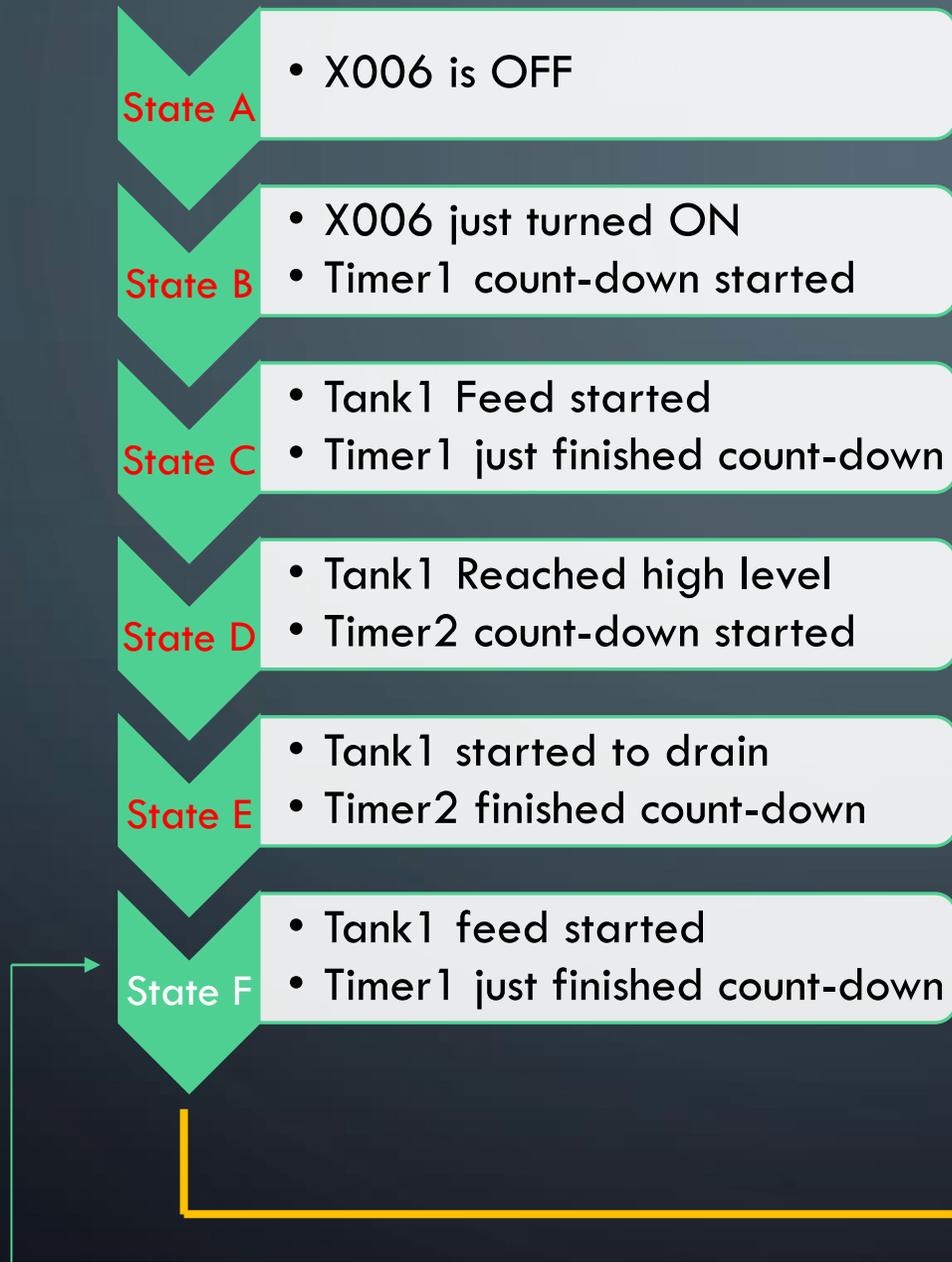
V3

L2

L1

L5

V4

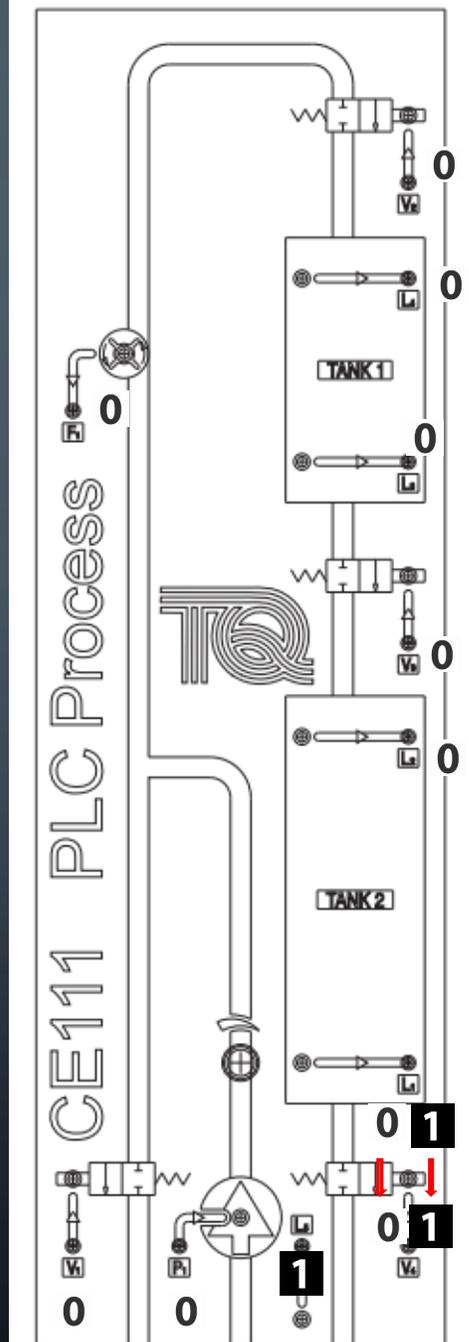
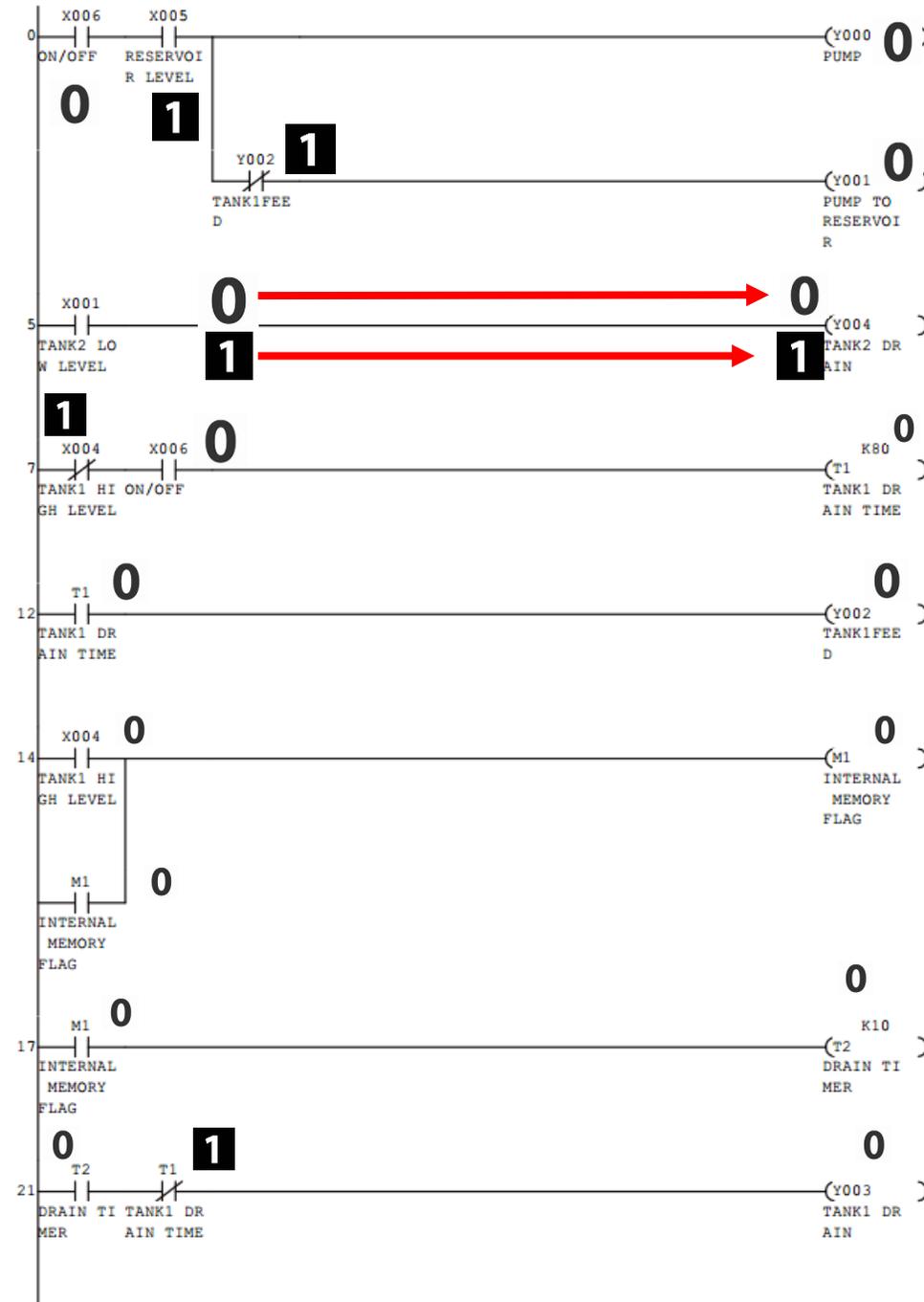


State G  
High Level



State H  
Drain

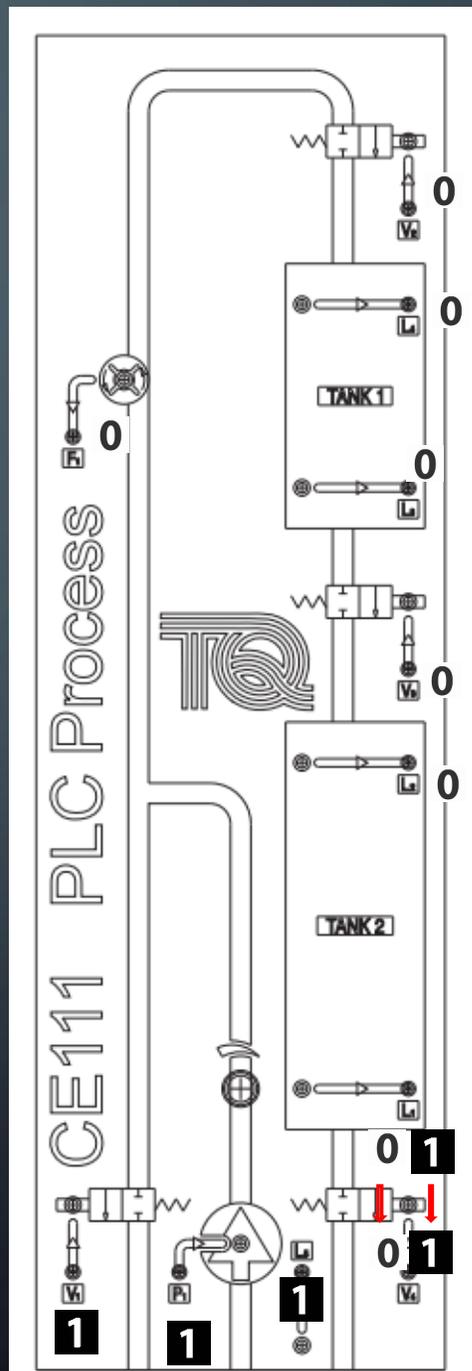
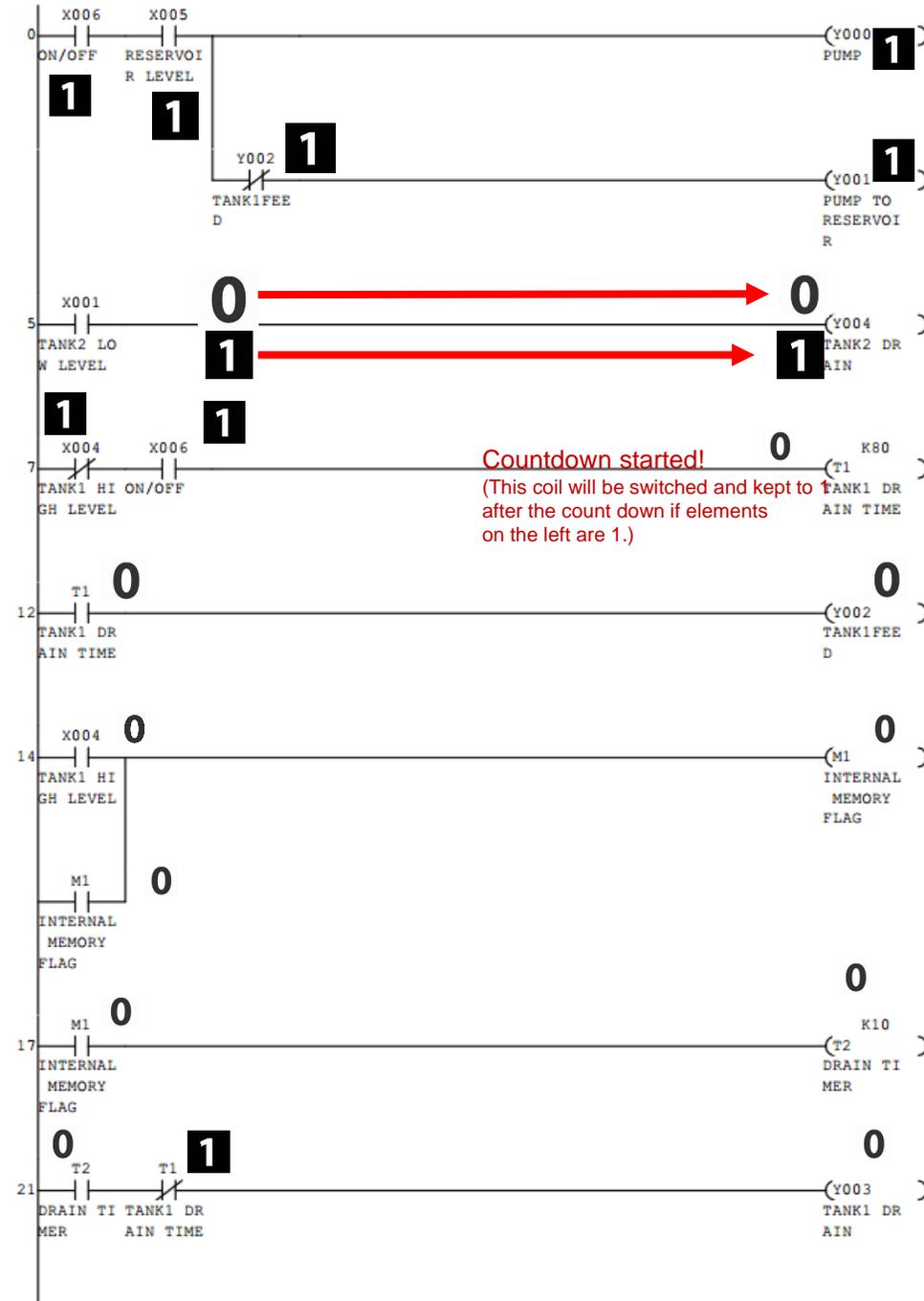
**State A:**  
 X006 was OFF  
 - Assume that  
 there is no water  
 in either tank.



**State B:**

X006 was just turned ON and T1 started the count-down process

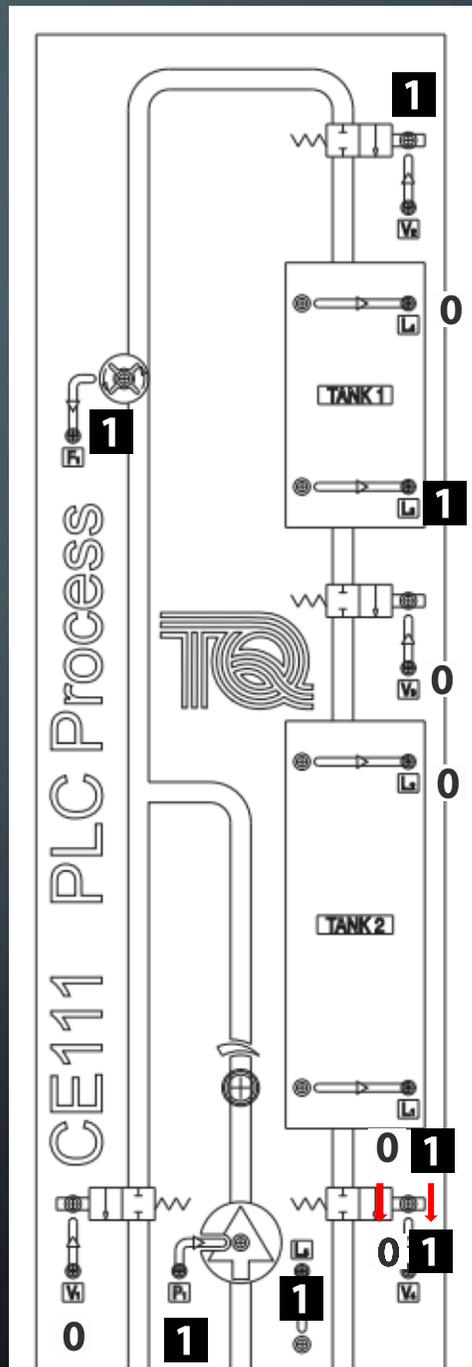
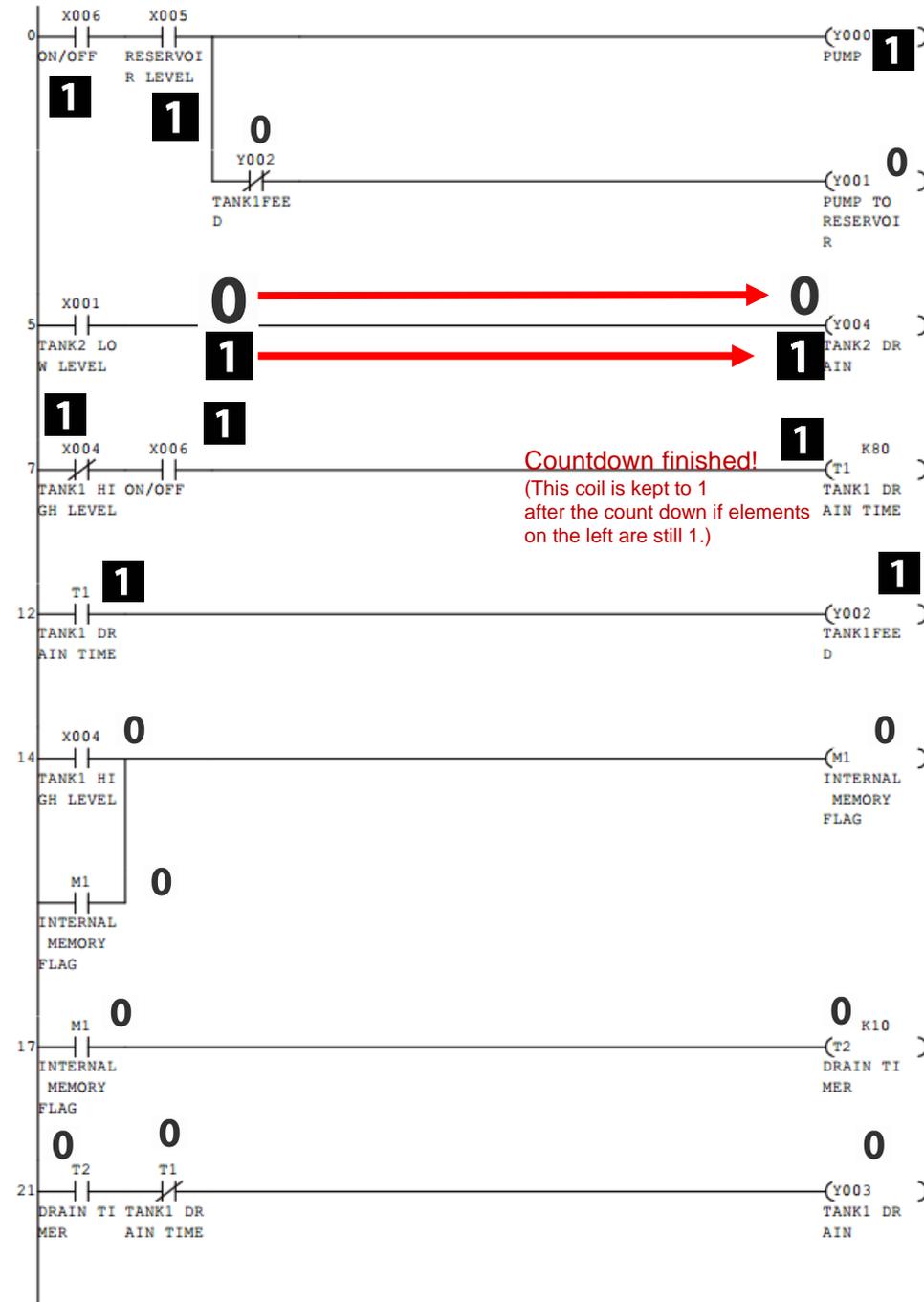
- Assume that there is no water in either tank.



### State C:

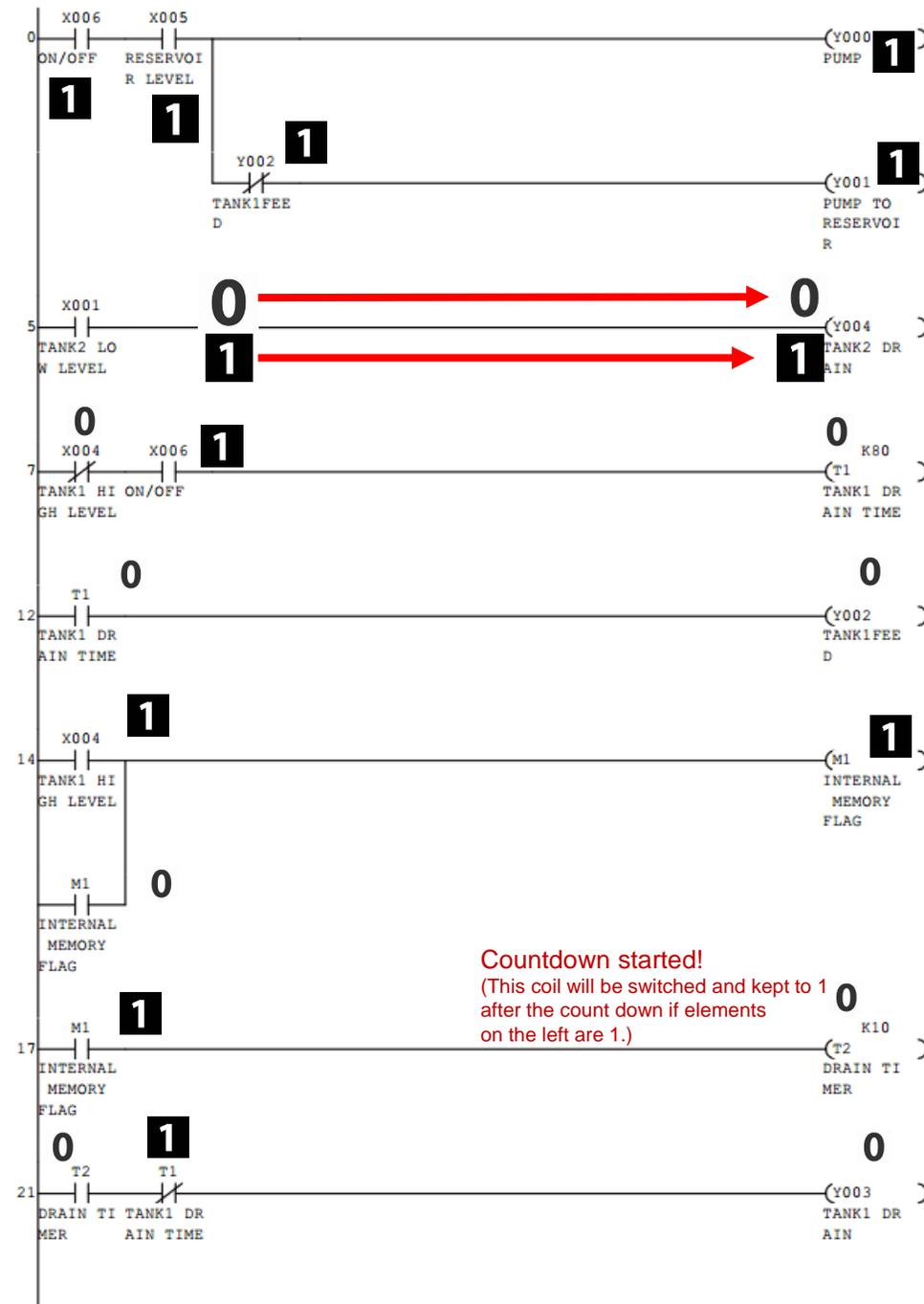
T1 just finished the count-down process and entered the feeding tank1 process

- Tank 1 is not full yet
- X006 keeps in ON mode

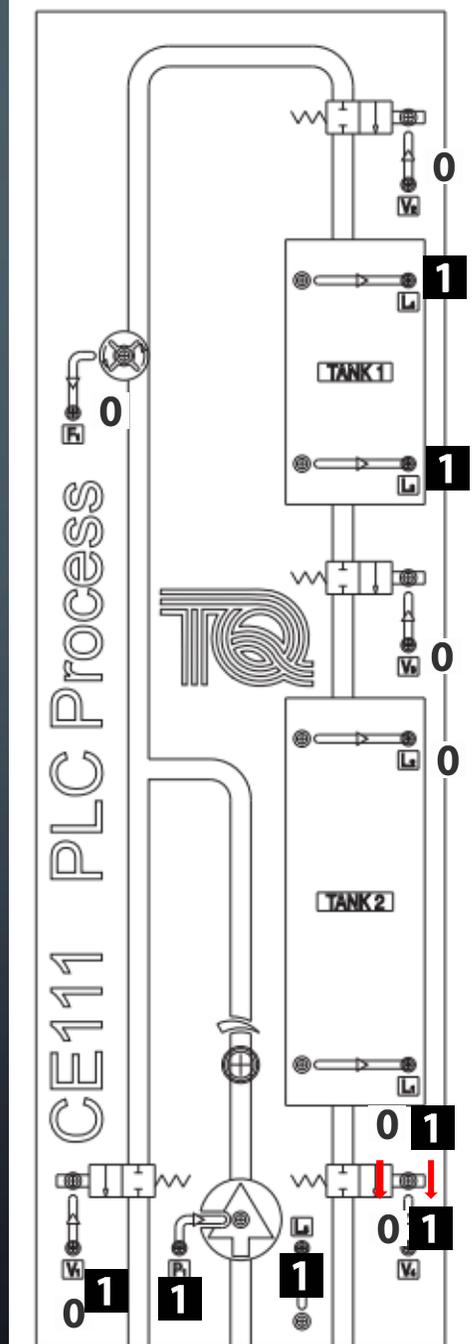


**State D:**  
Water in Tank 1  
had just reached  
the high level

- The feed  
stopped  
immediately
- T2 enters  
count-down  
process



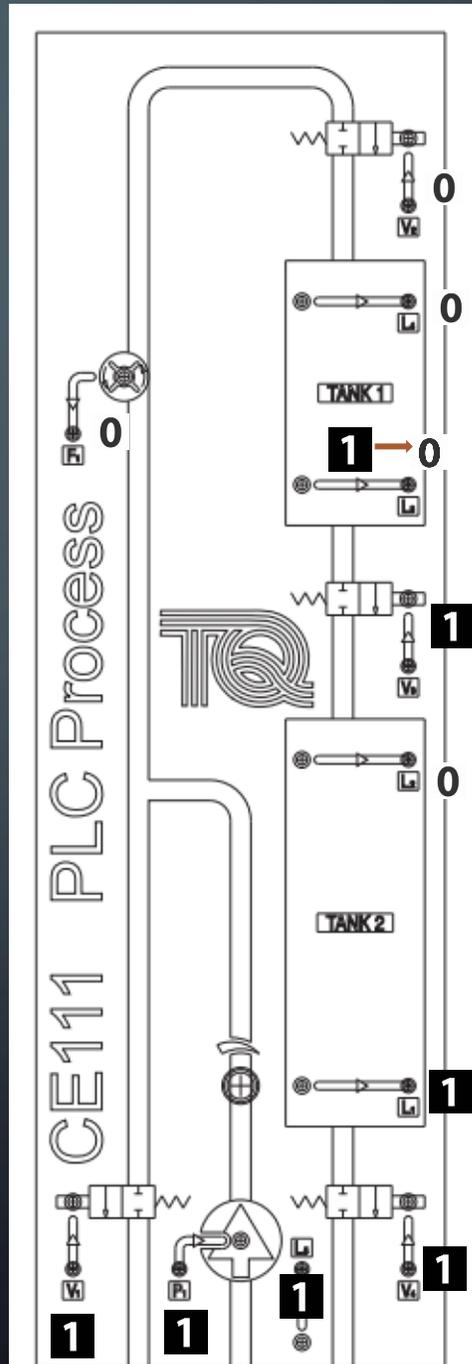
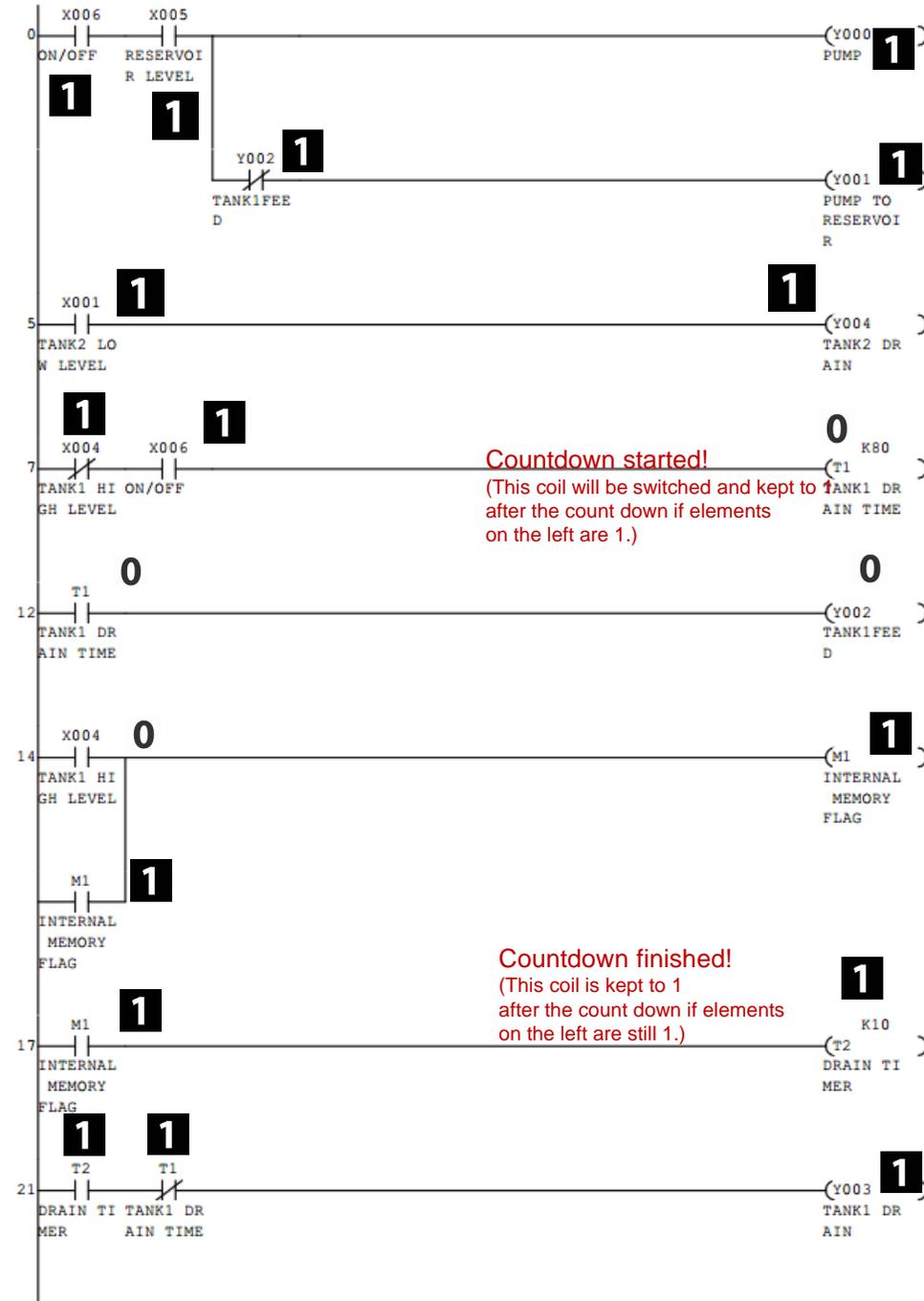
Countdown started!  
(This coil will be switched and kept to 1  
after the count down if elements  
on the left are 1.)



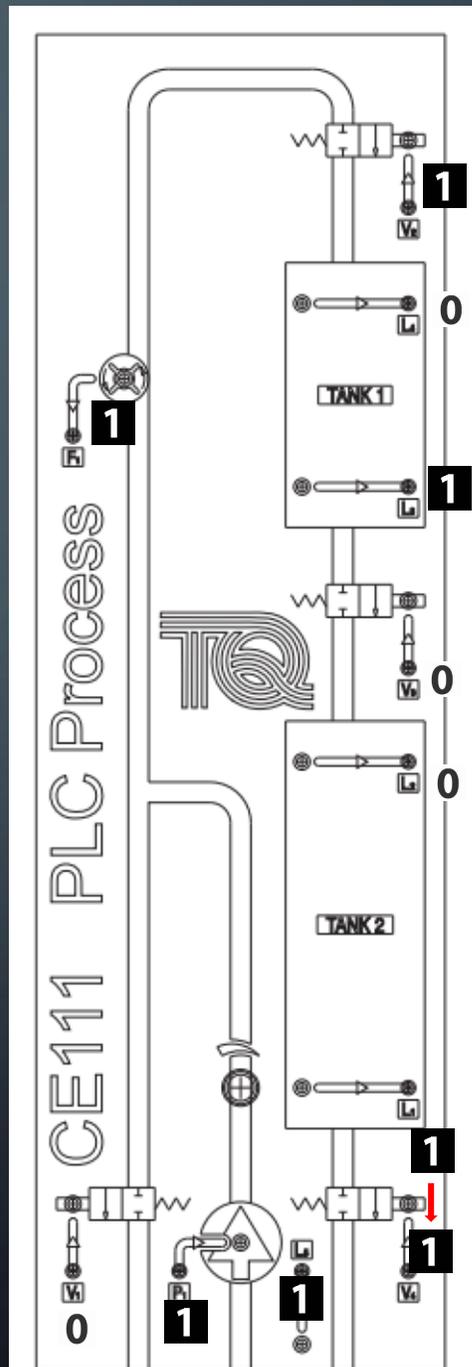
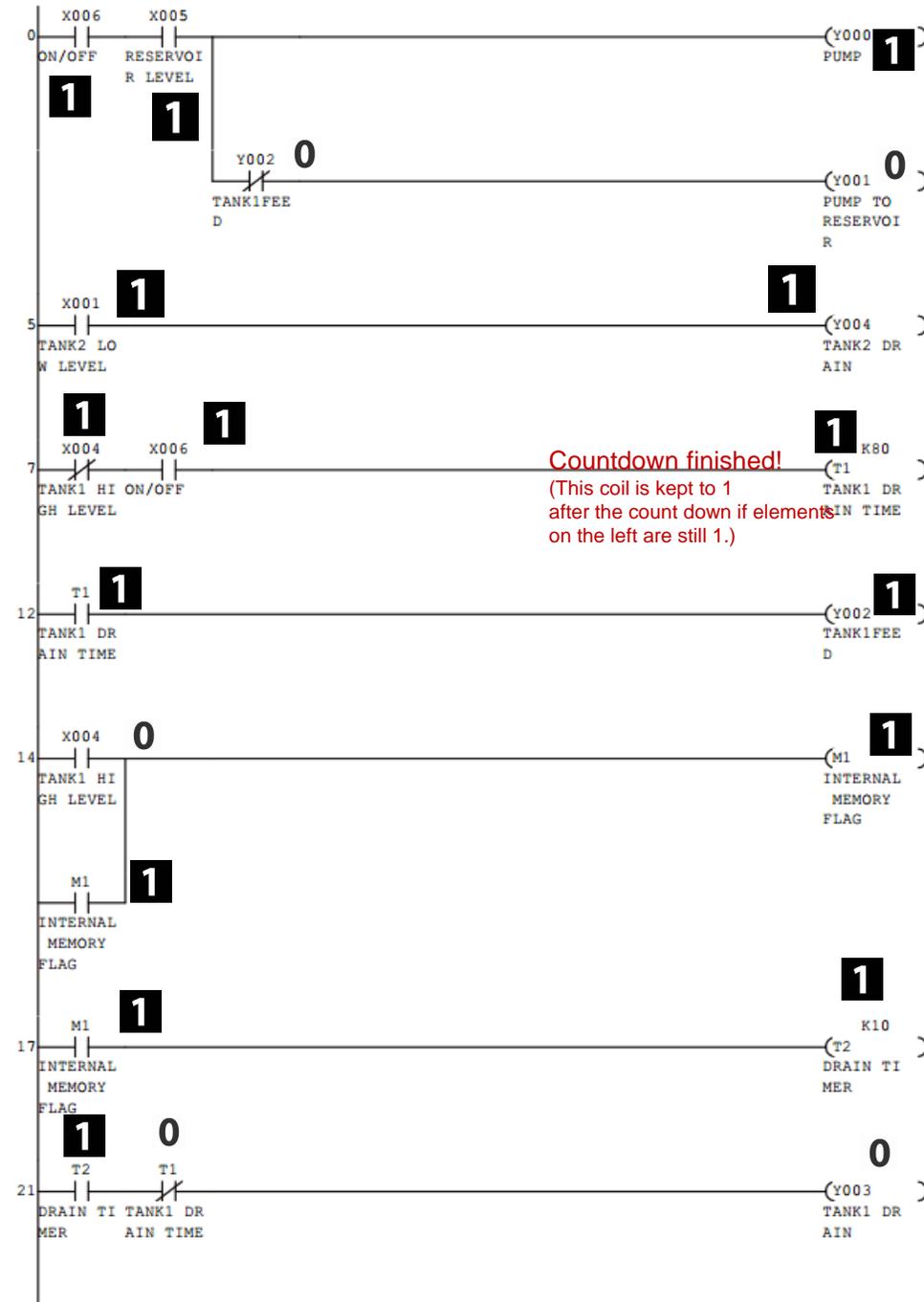
### State E:

T2 finished count-down and Tank 1 started to drain

- Water in Tank 1 dropped lower than high level
- T1 entered count-down process

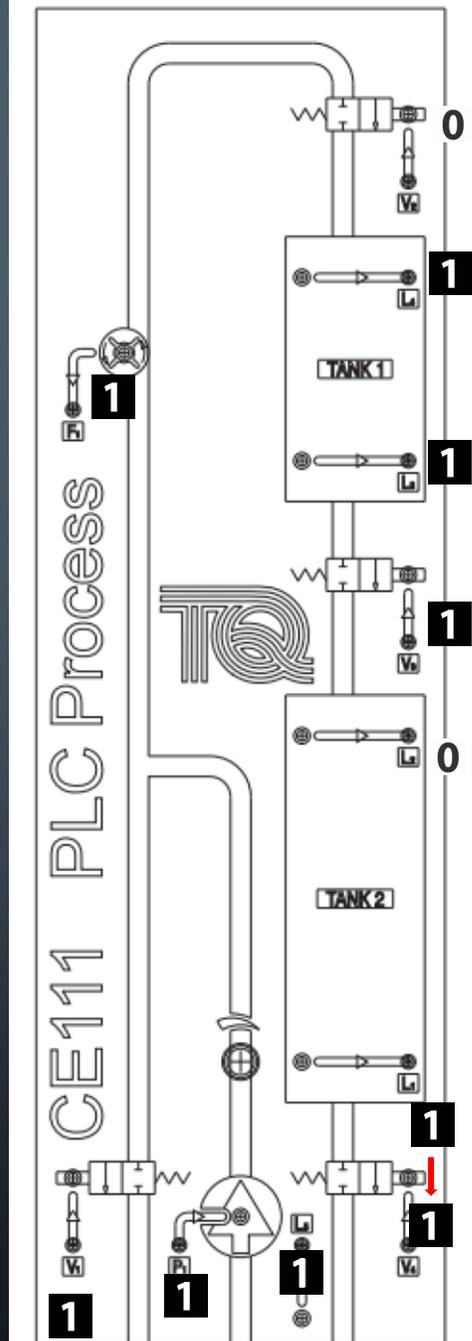
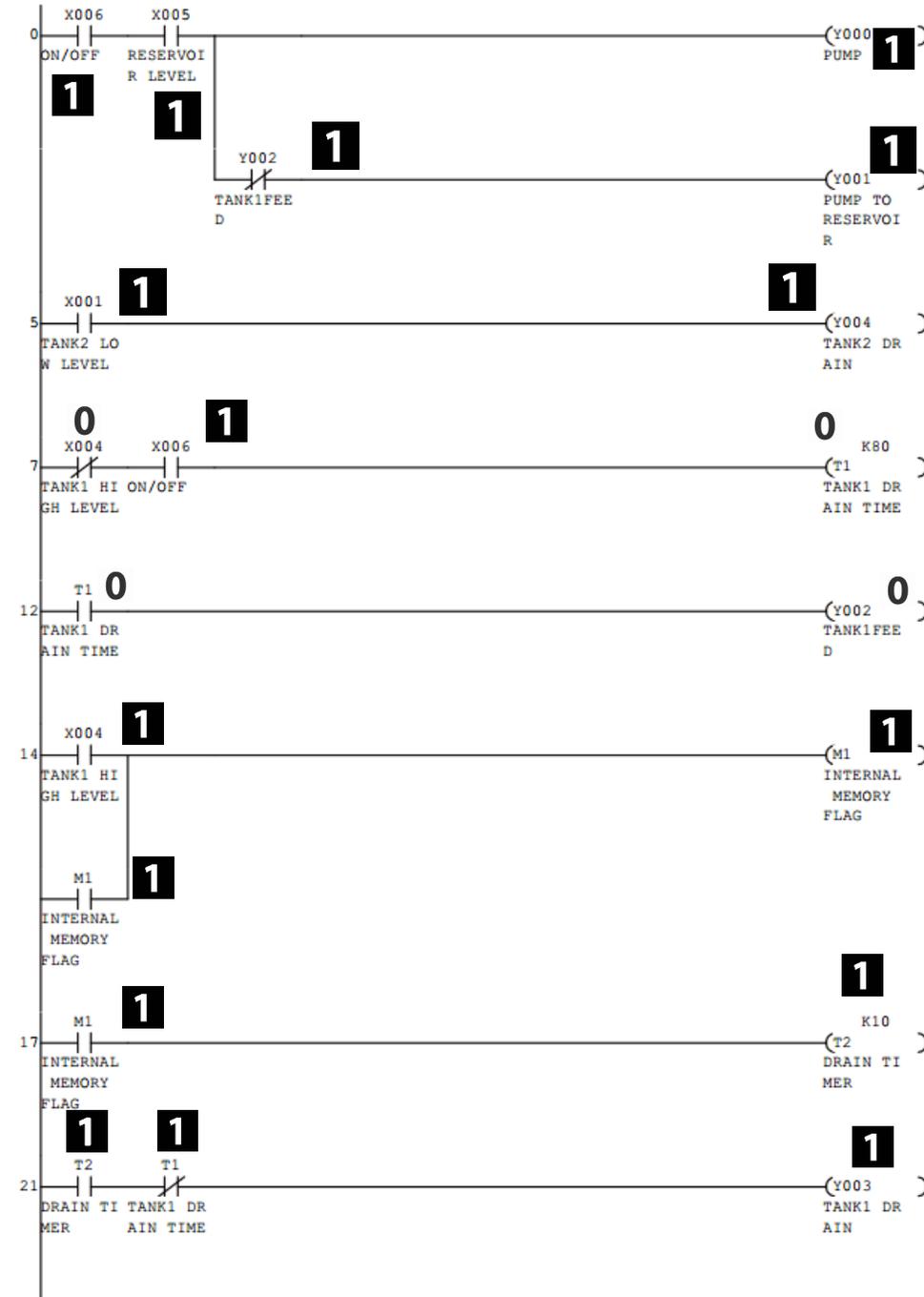


**State F:**  
 T1 finished  
 count-down,  
 drain stopped,  
 and started to  
 feed Tank 1

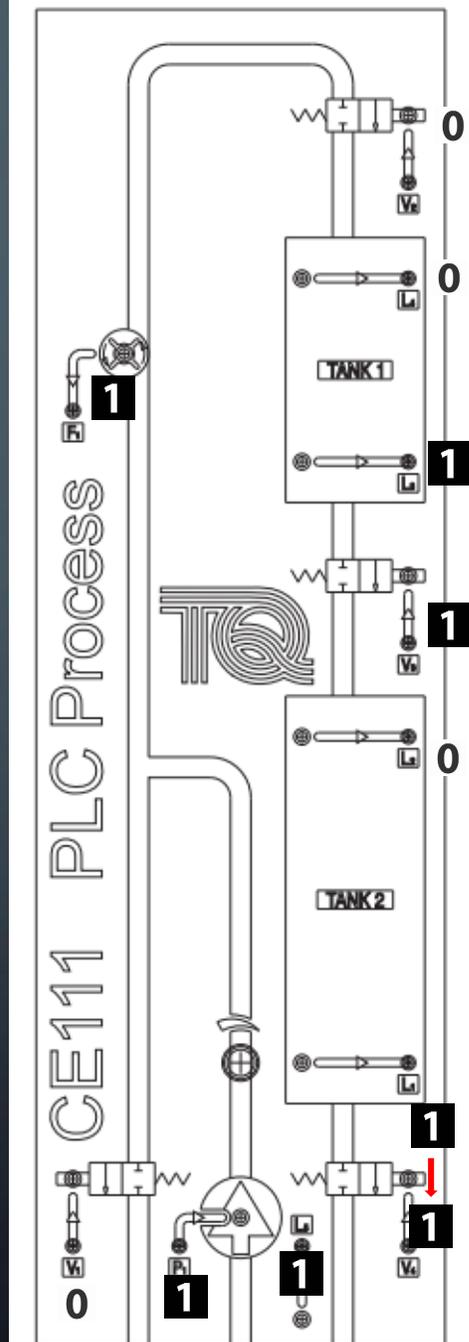
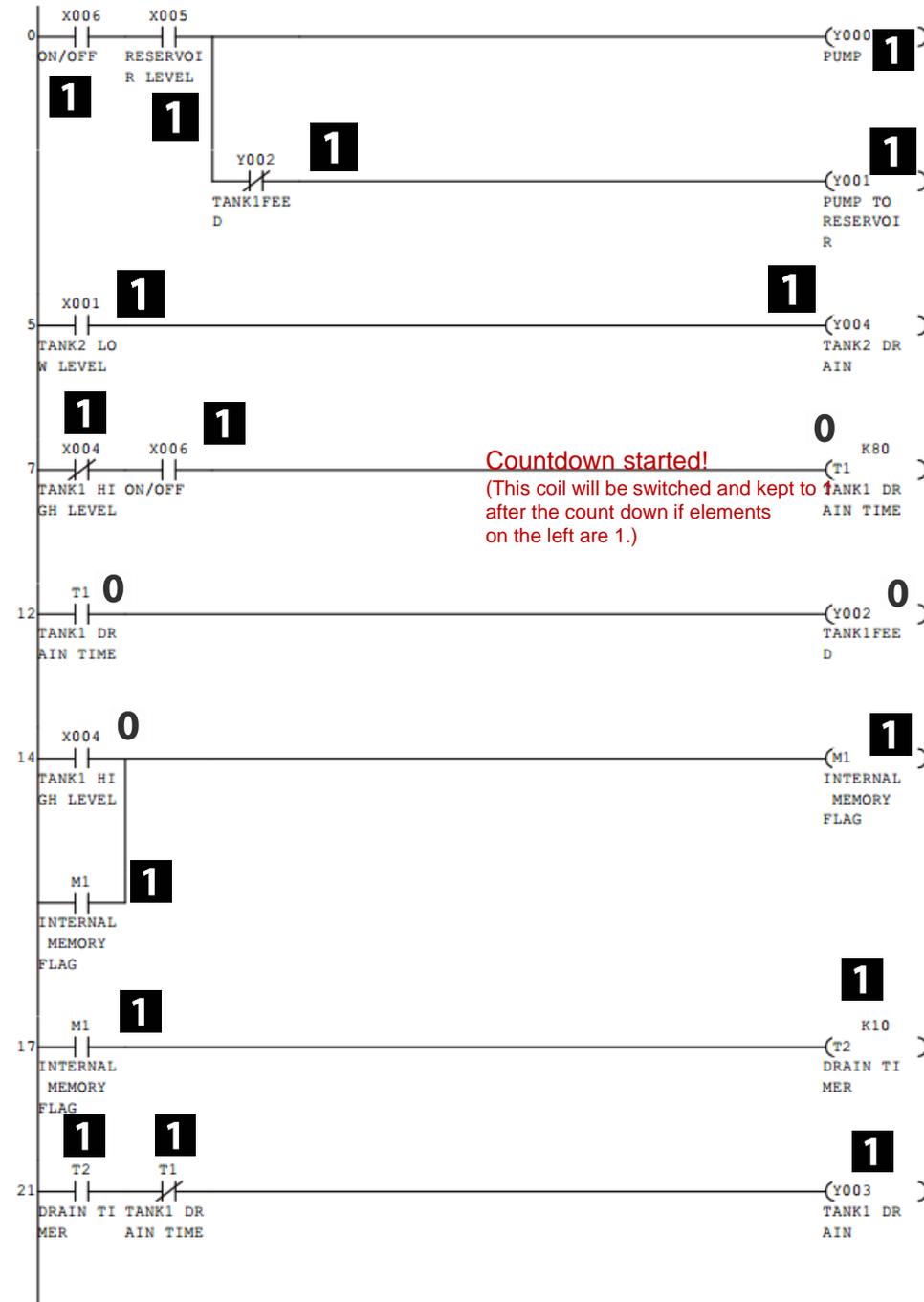


**State G:**  
Water in Tank 1 had just reached the high level

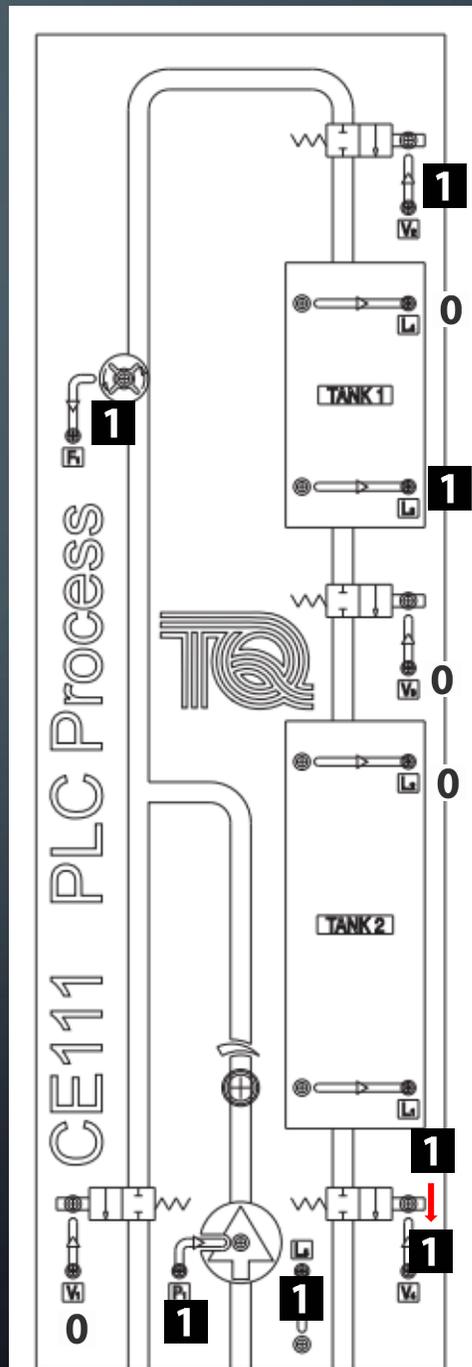
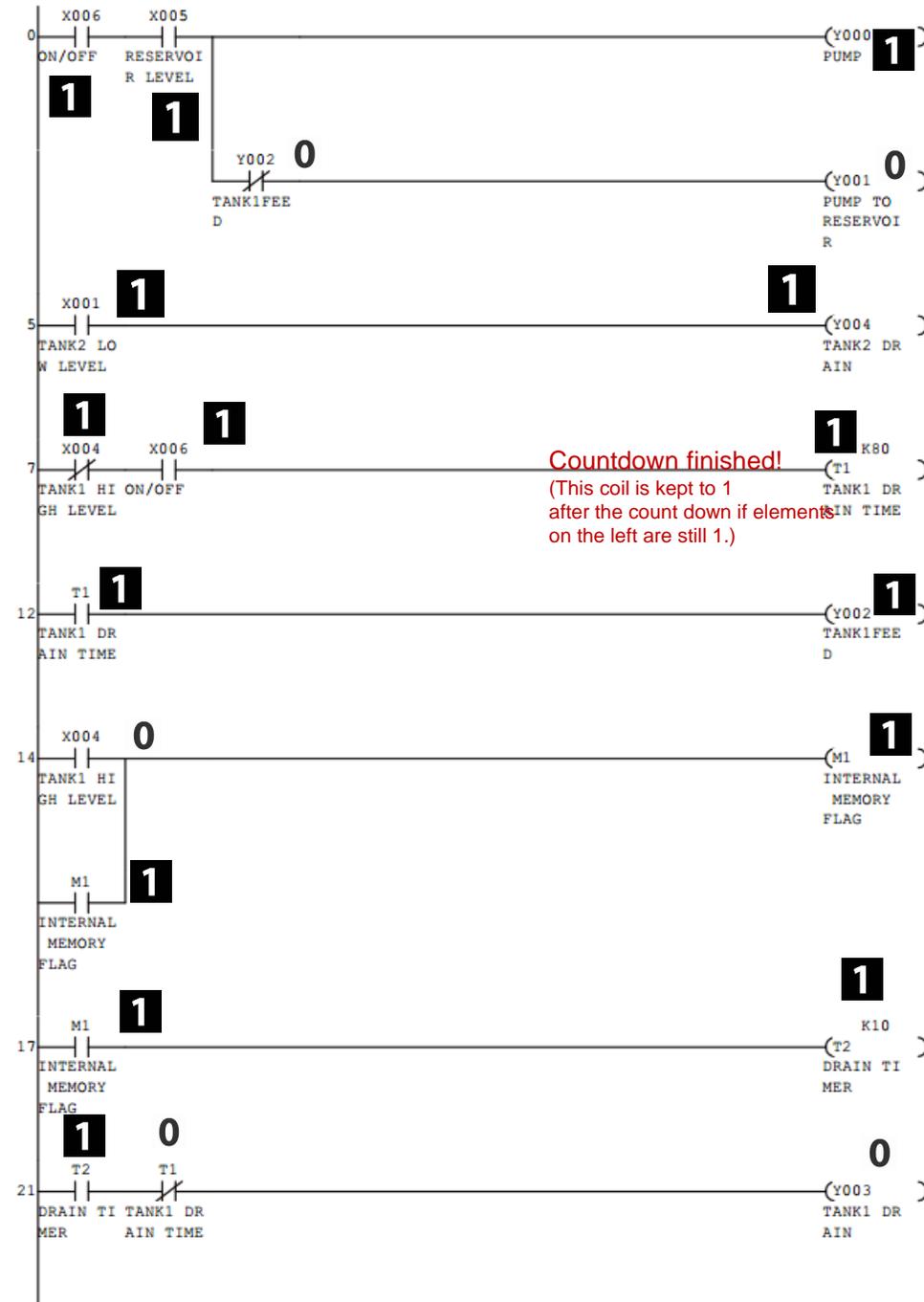
- The feed stopped immediately
- Timer1 reset to zero
- Tank1 Drain just started



**State H:**  
 Water in Tank 1  
 was draining  
 from high level

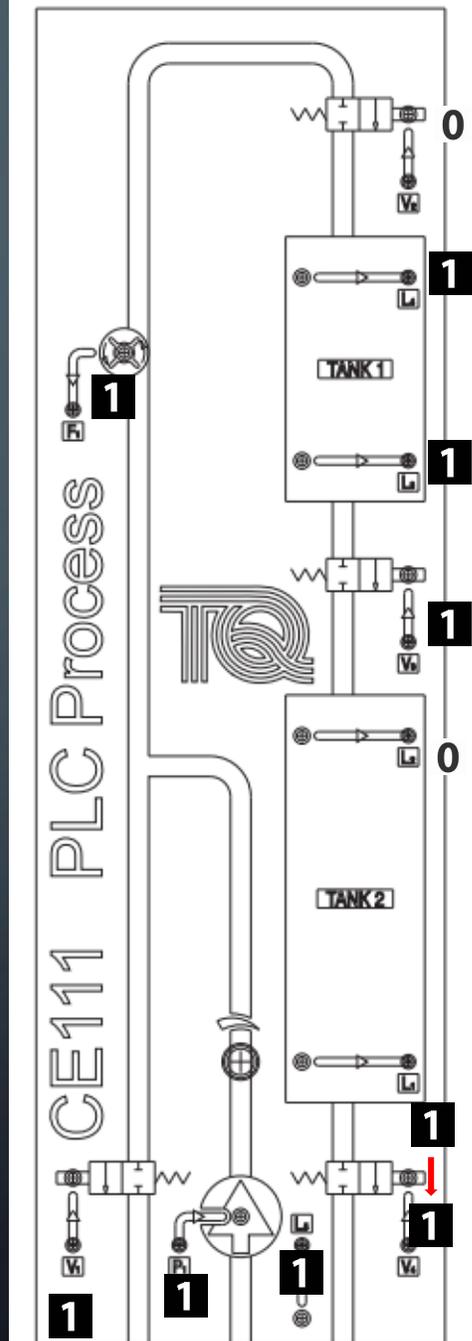
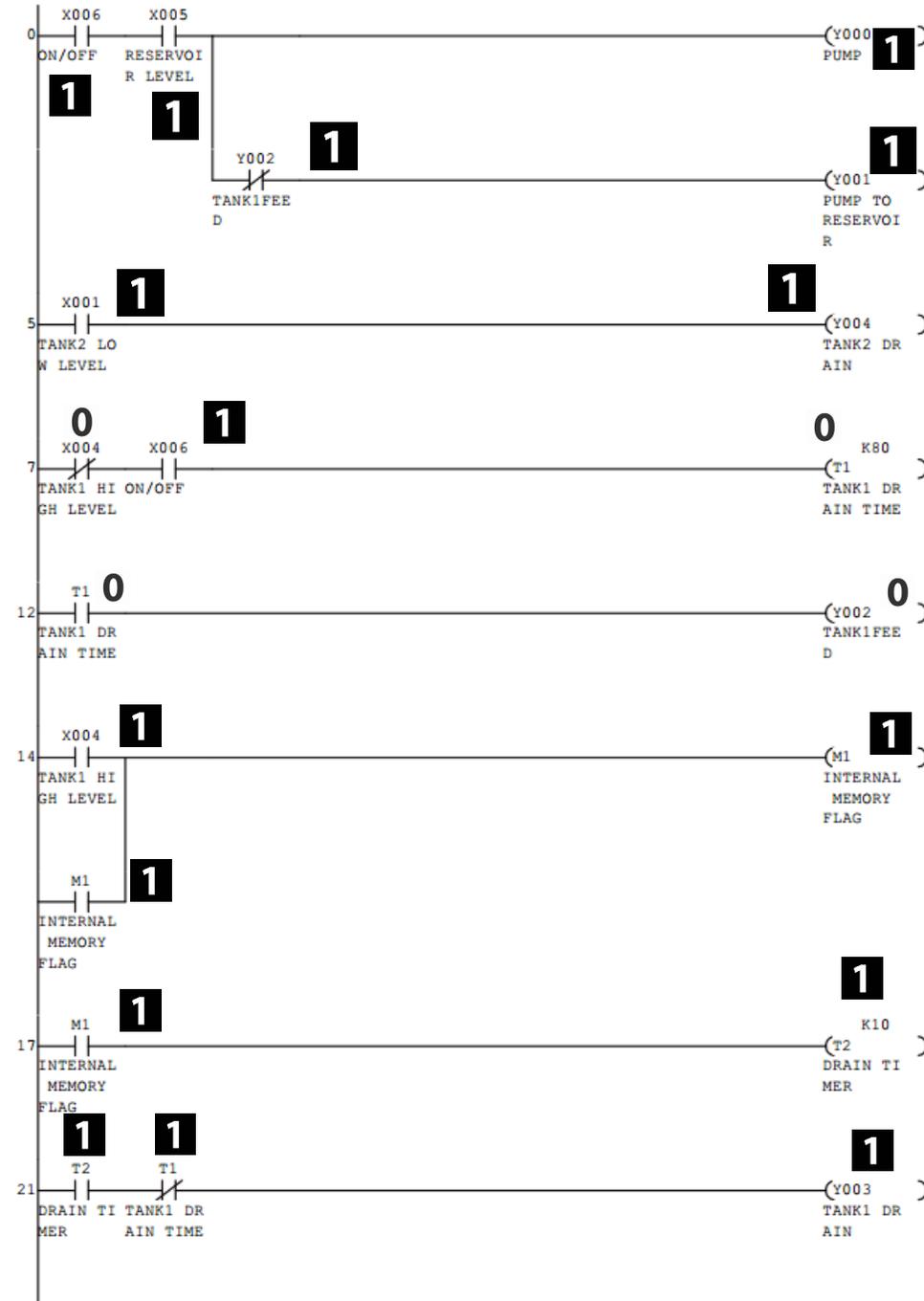


**State F:**  
 T1 finished  
 count-down,  
 drain stopped,  
 and started to  
 feed Tank 1

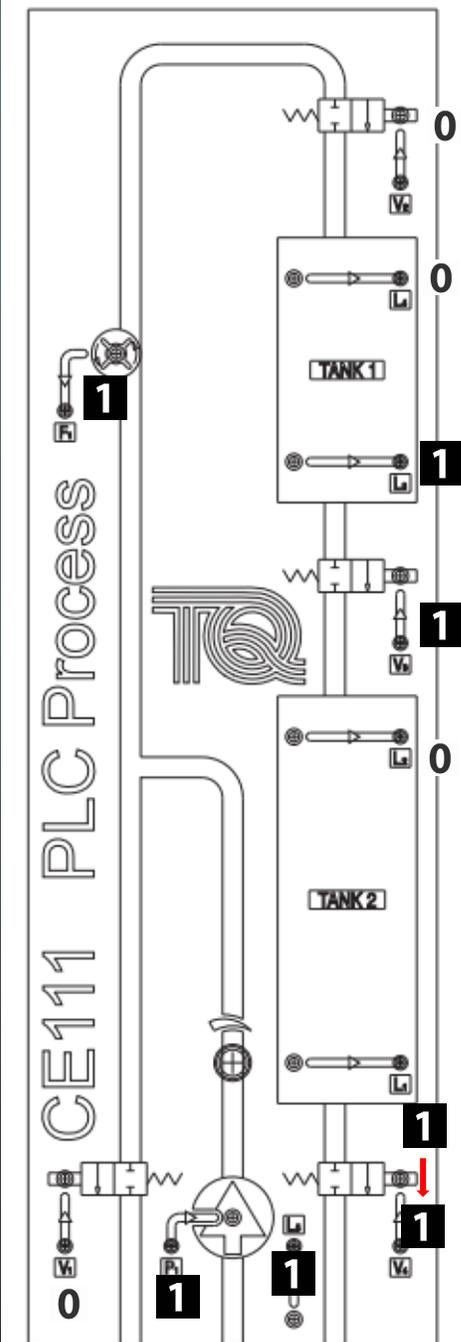
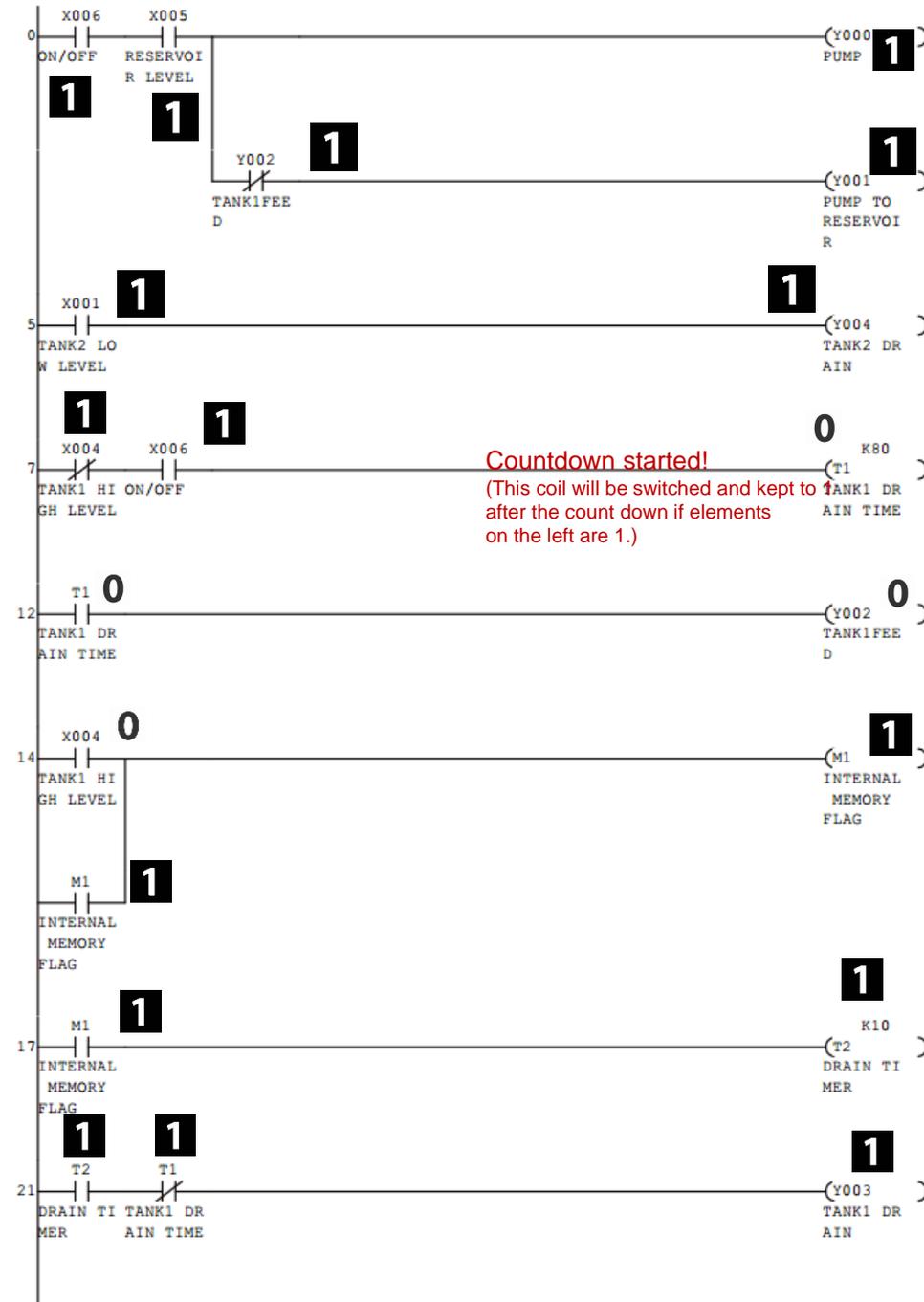


**State G:**  
 Water in Tank 1  
 had just reached  
 the high level

- The feed  
 stopped  
 immediately
- Timer1 reset  
 to zero
- Tank1 Drain  
 just started



**State H:**  
 Water in Tank 1  
 was draining  
 from high level



The image features a dark blue gradient background with white line-art patterns of circuit boards in the corners. The top-left and bottom-left corners have more complex, branching patterns, while the top-right and bottom-right corners have simpler, more linear patterns.

KEEP LOOPING IN  
STATES OF **F G H**

