

Instructor: Ping C. Sui, Ph.D. ME 1029 Mechanical Design 2

Fall 2021

What is the definition of Static Failure?

Obviously fracture is a form of failure



In some components yielding can also be considered as failure, if yielding distorts the material in such a way that it no longer functions

properly



Session Outlines

- Review failure criteria for <u>ductile</u> materials under <u>static</u> <u>loading</u> (Sec. 5-3 to 5-5, 5-7)
 - Maximum Shear Stress Theory
 - Distortion Energy Theory
- Calculate critical stresses
- Review characteristic stresses under press-fit
- Apply failure theories for press-fit pass/fail assessment

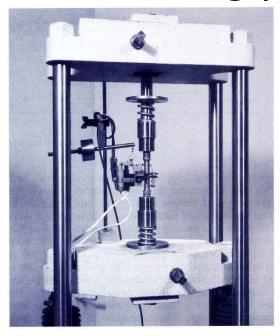


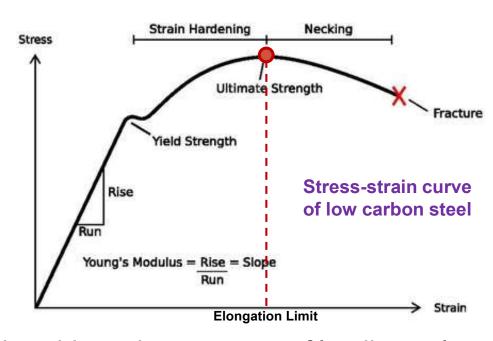
Technical Overview

- A static load is a stationary force or couple applied to a member.
 - To be stationary, the force or couple must be unchanging in magnitude, application locations, and direction.
 - A static load can produce axial tension or compression, a shear load, a bending load, a torsional load, or any combination of these.
- Strength is a property or characteristic of a mechanical element, which is the <u>resistance</u> to failure of a mechanical element.

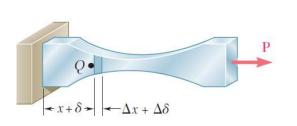


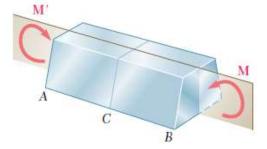
Material Testing (ASTM E8 Uniaxial Tensile Test)

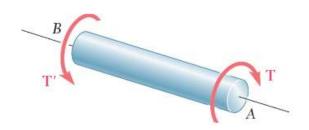




 <u>Uniaxial Loading</u> – System is subjected to one type of loading only: axial tension/compression, bending, or torsion.

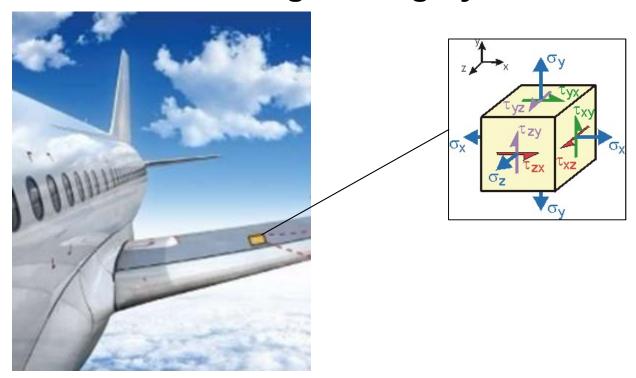




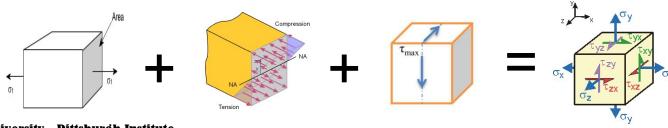




Stress Element in Engineering Systems



 <u>Multiaxial Loading</u> – In a real engineering system, loading condition is usually more complicated than simple loading. Multiple loading types simultaneously acting on the system is more typical.



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Failure Prediction vs. Failure Testing

- Ideally, failure prediction should be based on data collected from full-sized prototype testing under application environment.
- In reality, it is usually benchmarked against criteria established from test data collected from simple "coupon" testing.



Failure Predictions Theories

5-4 Maximum-Shear-Stress Theory for Ductile Materials

5-5 Distortion-Energy Theory for Ductile Materials

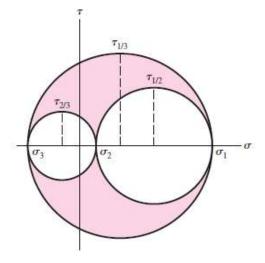


Failure Prediction Theories

Maximum-Shear-Stress Theory

Failure occurs whenever the maximum shear stress (τ_{max}) in a design part exceeds the max shear stress at yield point in a tensile test specimen of the same material

$$\tau_{max} = \frac{\sigma_1 - \sigma_3}{2}$$



Distortion-Energy Theory (DET)

Failure is assumed to occur
 whenever the octahedral shear
 stress (τ_{oct}) for any stress
 state equals or exceeds the
 octahedral shear stress for the
 simple tension-test specimen
 at yield point.

$$\tau_{oct} = \frac{\sqrt{2}}{3}\sigma_e$$

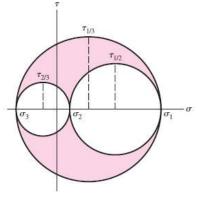
$$= \frac{1}{3}[(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]^{1/2}$$

Maximum-Shear-Stress (Tresca) Theory

Design Part

• Given $\sigma_1 > \sigma_2 > \sigma_3$, maximum shear stress is (Sec. 3-7)

$$(\tau_{max})_{design} = \frac{\sigma_1 - \sigma_3}{2}$$



Simple Tension Test

- For simple tension test (ASTM E8) at yield, $\sigma_1 = S_v$, $\sigma_2 = \sigma_3 = 0$.
- Thus maximum shear stress theory predicts that failure will occur when $(\tau_{max})_{E8} = \frac{S_y}{2}$ or $\sigma_1 \sigma_3 = S_y$
- DET assumed design part reaches failure point when

$$(\tau_{max})_{design} \ge (\tau_{max})_{E8} = \frac{S_y}{2}$$

To incorporate a factor of safety, n:

$$n = \frac{(\tau_{max})_{E8}}{(\tau_{max})_{design}} = \frac{\frac{S_y}{2}}{(\tau_{max})_{design}} = \frac{S_y}{(\sigma_1 - \sigma_3)_{design}}$$

Example

A hot-rolled steel has a yield strength of S_y = 100 ksi. And is subjected to the stress states of σ_x = 70 ksi, σ_y = 70 ksi, τ_{xy} = 0 kpsi What is its safety factor per Max Shear Theory?

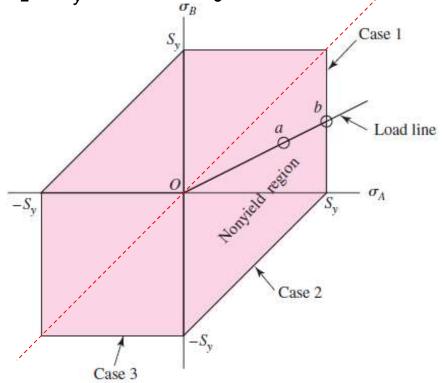


Example

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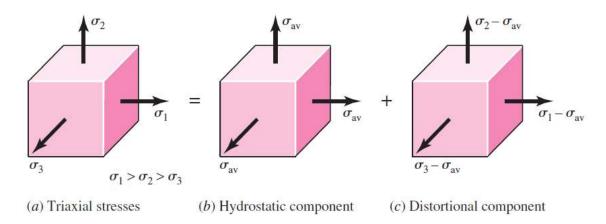
- hot-rolled steel ➤ Ductile material
- Since $\tau_{xy} = 0$; $\blacktriangleright \sigma_1 = \sigma_x = 70$ ksi $\blacktriangleright \sigma_2 = \sigma_y = 70$ ksi, $\sigma_3 = 0$ $\tau_{max} = \frac{\sigma_1 \sigma_3}{2} = \frac{70 0}{2} = 35 \text{ ksi}$
- Safety Factor n

$$n = \frac{s_y/2}{\tau_{max}} = \frac{100/2}{35} = 1.43$$



Distortion-Energy Theory (DET)

• Materials can take enormous hydrostatic pressures (e.g., rocks deep in the earth that see pressures well above their compressive strength) and not fracture – suggesting that it must be <u>distortion</u> that causes failure.



- DET essentially computes the total strain energy and subtracts the volume change energy to get the distortion energy.
- Refer to Sec. 5-5 for detailed derivation of the von Mises stress using xyz three-dimensional stress

Distortion-Energy Theory (DET)

Failure is assumed to occur whenever the octahedral shear stress (τ_{oct}) for any stress state equals or exceeds the octahedral shear stress for the simple tension-test specimen at yield point.

Design Part

Design Part

von Mises equivalent stress
$$\sigma_e = \frac{1}{\sqrt{2}} \left[(\sigma_x - \sigma_y)^2 + (\sigma_y - \sigma_z)^2 + (\sigma_z - \sigma_x)^2 + 6(\tau_{xy}^2 + \tau_{yz}^2 + \tau_{zx}^2) \right]^{1/2}$$
or in principal stresses: $\sigma_z = \frac{1}{2} \left[(\sigma_z - \sigma_z)^2 + (\sigma_z - \sigma_z)^2 + (\sigma_z - \sigma_z)^2 \right]^{1/2}$

or in principal stresses: $\sigma_e = \frac{1}{\sqrt{2}} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]^{1/2}$

Octahedral shear stresses

$$(\tau_{oct})_{design} = \frac{\sqrt{2}}{3}\sigma_e = \frac{1}{3}[(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]^{1/2}$$

Simple Tension Test

• $(\sigma_1 = S_v, \sigma_2 = \sigma_3 = 0)$. The τ_{oct} at yield point under simple tension is

$$(\tau_{oct})_{E8} = \frac{\sqrt{2}}{3} S_y$$



Distortion-Energy Theory (DET)

DET assumed design part reaches failure point when

$$(\tau_{oct})_{design} \ge (\tau_{oct})_{E8} = \frac{\sqrt{2}}{3} S_y$$

When using von Mises equivalent stress, this also reduces to
$$\sigma_e = \frac{1}{\sqrt{2}}[(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]^{1/2} \ge S_y$$

$$\sigma_e = \frac{1}{\sqrt{2}} \left[\left(\sigma_x - \sigma_y \right)^2 + \left(\sigma_y - \sigma_z \right)^2 + (\sigma_z - \sigma_x)^2 + 6 \left(\tau_{xy}^2 + \tau_{yz}^2 + \tau_{zx}^2 \right) \right]^{1/2} \ge S_y$$

- Safety Factor n: $n = \frac{S_y}{\sigma}$
- Note that, under hydrostatic pressure case ($\sigma_1 = \sigma_2 = \sigma_3$), von Mises equivalent stress $\sigma_{e}=0$. DET predicts no failure occurred.

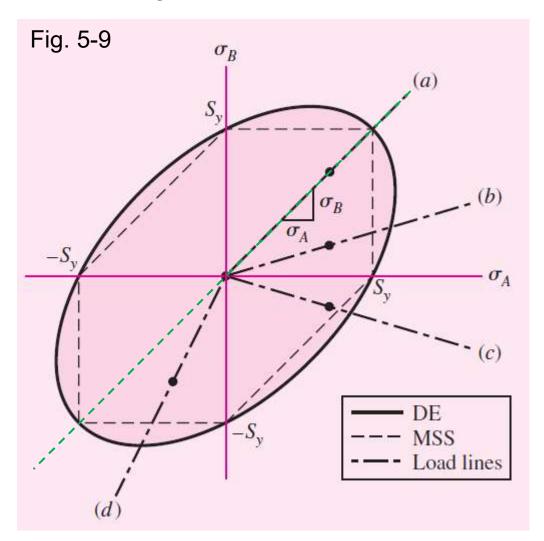
Graphical Illustration of DET Theory Under Plane Stress

Under plane stress state (σ_3 =0):

$$\sigma_{e} = [\sigma_{1}^{2} - \sigma_{1}\sigma_{2} + \sigma_{2}^{2}]^{1/2} \ge S_{y}$$

$$\sigma_{e} = [\sigma_{x}^{2} - \sigma_{x}\sigma_{y} + \sigma_{y}^{2} + 3\tau_{xy}^{2}]^{1/2} \ge S_{y}$$

- Factor of safety, n: $n = \frac{S_y}{\sigma_e}$
- MSS Theory provides a <u>lower SF</u> than DET in most cases.
- Case (a) is a special case where SF from MSS is identical to SF from DET





Example

Example: A hot-rolled steel has a yield strength of S_y = 100 ksi. And is subjected to the stress states of

(a)
$$\sigma_x = 70$$
 ksi, $\sigma_y = 70$ ksi, $\tau_{xy} = 0$ kpsi

What is its safety factor per Distortion Energy Theory?

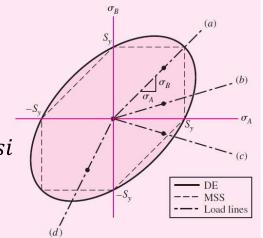
Solution:

$$\sigma_e = \frac{1}{\sqrt{2}} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]^{1/2}$$

$$\sigma_e = [\sigma_1^2 - \sigma_1 \sigma_2 + \sigma_2^2]^{1/2} = [70^2 - 70 * 70 + 70^2]^{1/2} = 70 \text{ Ksi}$$

$$Safety\ Factor = \frac{100}{70} = 1.43$$

Note that, in this case, SF from DET is the same as MSS

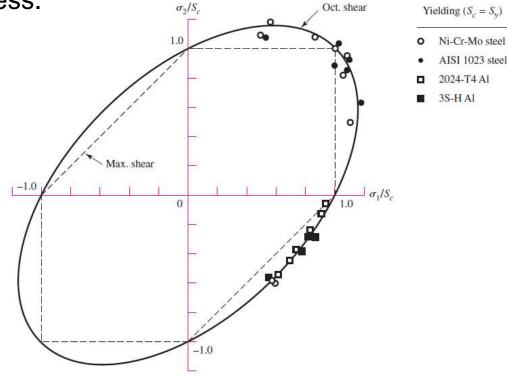


MSS versus **DET** Comparison

- Historical test data indicates that DET is more accurate than MSS in predicting failure point than MSS.
- DET is a prevailing design criteria.

However, MSS does use when applications warrant greater

conservativeness.



Press-Fit Failure Assessment

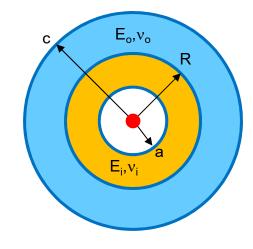
 Apply characteristic stresses resulting from press-fit to MSS and DET failure theories



Stresses at Press Fit Interface

Interfacial Contact Pressure

$$P = \frac{\delta}{b \left[\frac{1}{E_o} \left(\frac{c^2 + R^2}{c^2 - R^2} + \nu_o \right) + \frac{1}{E_i} \left(\frac{R^2 + a^2}{R^2 - a^2} - \nu_i \right) \right]}$$



Radial Stress
$$(\sigma_r)_{b_i} = (\sigma_r)_{b_o} = -P$$

Hoop Stress

$$(\sigma_{\theta})_{b_i} = -P \frac{R^2 + a^2}{R^2 - a^2}$$

$$(\sigma_{\theta})_{b_0} = P \frac{c^2 + R^2}{c^2 - R^2}$$

Note that:

- Critical stress is at the interference-fit interface
- Weak link is the hub ID surface, not the shaft OD surface

Stress Distribution on Hub ID Surface

On hub ID surface, principal stresses are:

$$\sigma_r = -P < 0$$
 $\sigma_\theta = P \frac{c^2 + R^2}{c^2 - R^2} > 0$ $\sigma_z = 0$ $(\sigma_\theta > \sigma_z > \sigma_r)$

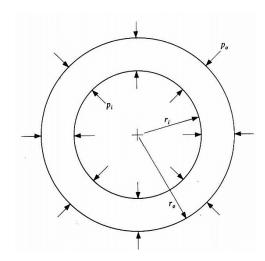
Per MSS criterion, press-fit fails @hub ID when:

$$\tau_{max} = \frac{\sigma_{\theta} - \sigma_{r}}{2} \ge \frac{S_{y}}{2} \qquad \frac{2c^{2}}{c^{2} - R^{2}}P \ge S_{y}$$

$$\frac{2c^2}{c^2 - R^2} P \ge S_y$$

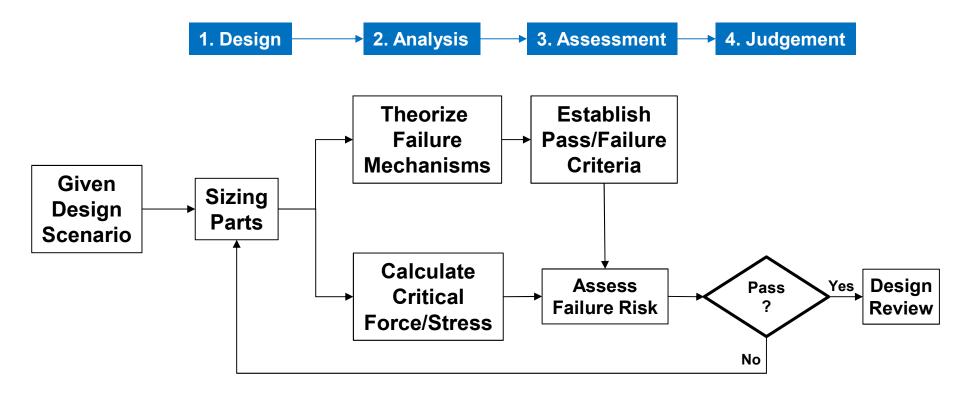
Per DET criterion, press-fit fails @hub ID when: $\sigma_e = \left[\sigma_{\rm r}^2 - \sigma_{\rm r}\sigma_{\rm \theta} + \sigma_{\rm \theta}^2\right]^{1/2} \geq S_y$

$$\sigma_e = \left[\sigma_{\rm r}^2 - \sigma_{\rm r}\sigma_{\theta} + \sigma_{\theta}^2\right]^{1/2} \ge S_y$$



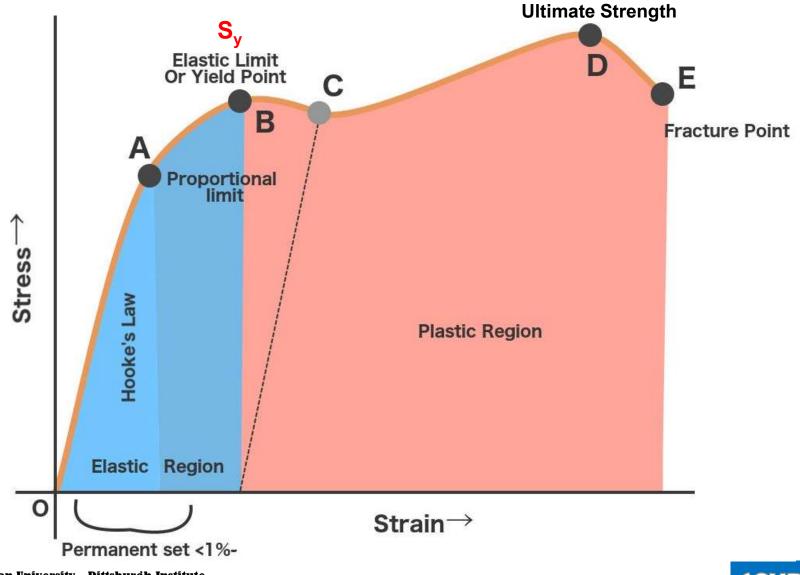
Design Workflow Discipline

Everything we do in this class, we will follow this discipline.....





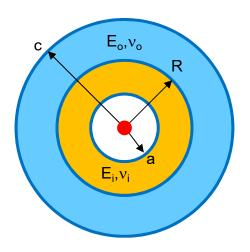
Typical Material Stress-Strain Curve



Example

An aluminum cylinder (E=70GPa, v=0.33) with an outer radius of 150mm and inner radius of 100mm, is press-fitted over a steel cylinder (E=200GPa, v=0.29) with an outer radius of 100.25 mm and inner radius of 50mm. Calculate safety factor of the design per MSS and DET criteria.

$$P = \frac{\delta}{b \left[\frac{1}{E_o} \left(\frac{c^2 + b^2}{c^2 - b^2} + \nu_o \right) + \frac{1}{E_i} \left(\frac{b^2 + a^2}{b^2 - a^2} - \nu_i \right) \right]}$$





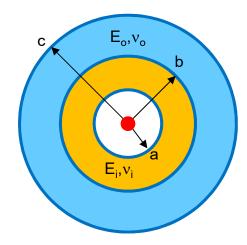
Example (Cont'd)

Solution:

Hub material: aluminum (E_0 =70GPa, v_0 =0.33)

Shaft material: steel (E_i =200GPa, v_i =0.29)

c=150mm; b=100mm; a=50mm; δ =0.25mm



$$P = \frac{0.25}{100 \left[\frac{1}{70000} \left(\frac{150^2 + 100^2}{150^2 - 100^2} + 0.33 \right) + \frac{1}{200000} \left(\frac{100^2 + 50^2}{100^2 - 50^2} - 0.29 \right) \right]} = 51.3 MPa$$

On hub ID surface, radial stress: $\sigma_r = -P = -51.3 \ MPa$

Hoop stress:
$$\sigma_{\theta} = P \frac{c^2 + b^2}{c^2 - b^2} = 51.3 \frac{150^2 + 100^2}{150^2 - 100^2} = 133.38 MPa$$

Assume hub material is T6 cast aluminum. Table A-24 shows that its typical yield strength $S_v = 165 MPa$

Example (Cont'd)

Solution:

Max shear stress on hub ID surface:

$$\tau_{max} = \frac{\sigma_{\theta} - \sigma_{r}}{2} = \frac{133.38 - (-51.3)}{2} = 92.34MPa$$

Safety factor per MSS: $n = \frac{165}{2.92.34} = 0.89 < 1$, which indicates hub will fail.

Equivalent stress on hub ID surface:

$$\sigma_e = \left[\sigma_{\rm r}^2 - \sigma_{\rm r}\sigma_{\theta} + \sigma_{\theta}^2\right]^{1/2} = \sqrt{(-51.3)^2 - (-51.3)(133.38) + 133.38^2} = 165 \, MPa$$

Safety factor per DET: $n = \frac{165}{165} = 1$, which indicates hub safety is marginal and leans towards the failure side.